



# Pilot kick-off event

Istanbul, April 2026

# FORD OTOSAN

## NextEtruck: Türkiye Pilot Use Case

Mustafa Başaran(Ford Otosan)  
[mbasara3@ford.com.tr](mailto:mbasara3@ford.com.tr)

Furkan Aksu (Ford Otosan)  
[faksu@ford.com.tr](mailto:faksu@ford.com.tr)



Co-funded by  
the European Union



Co-funded by  
UK Government

*This project has received funding from the European Union's Horizon Europe programme under grant agreement No 101056740*

Next  
Etruck



# Enabling Next-Gen Electric Truck Platforms





# Shaping The Future of Electric Mobility

- 6.000 kg curb weight with 10.000 kg payload
- Aluminum & modular e-platform
- EPS for trucks as first demo in market

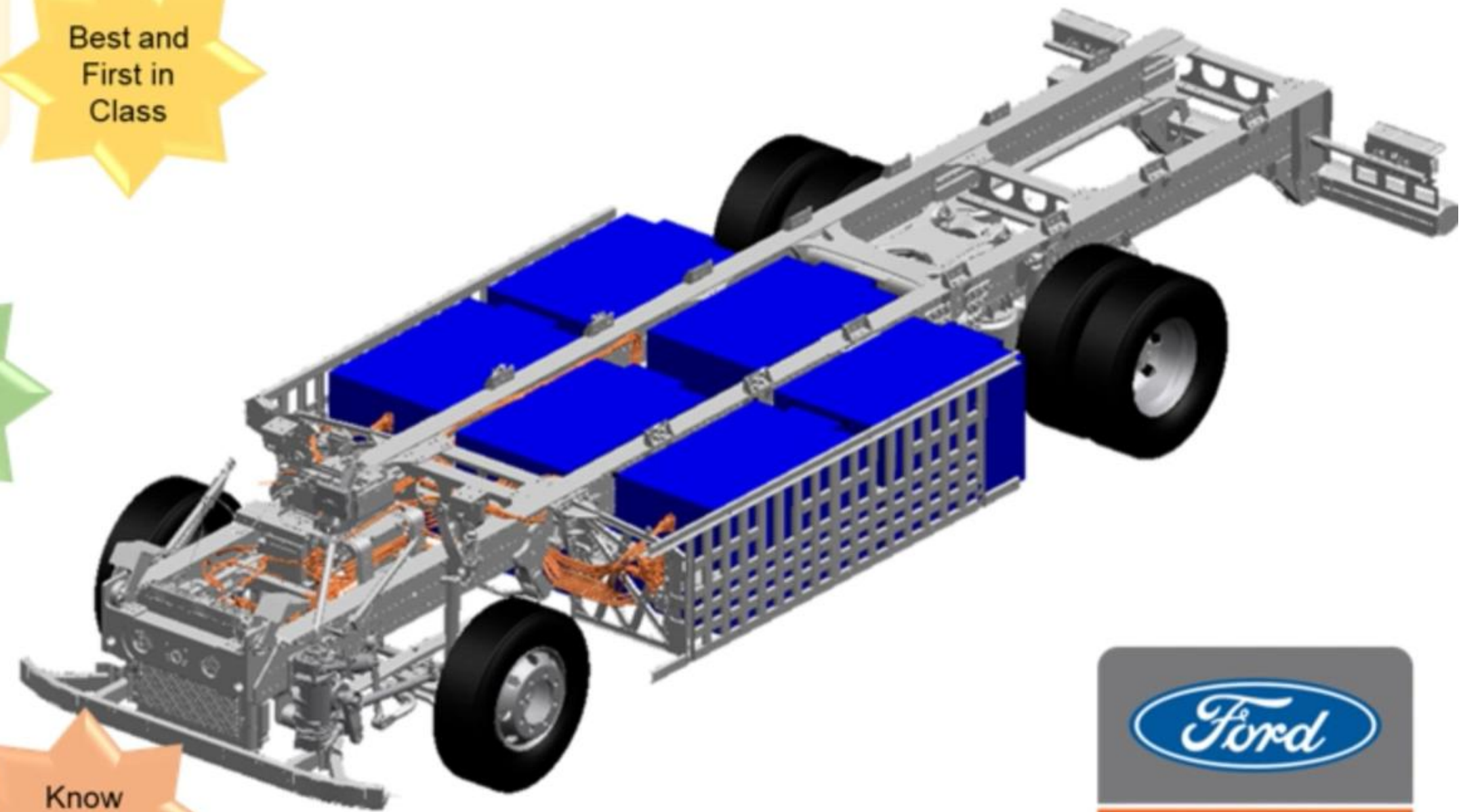
Best and  
First in  
Class

- AVAS development for BEV trucks
- New battery packaging strategy
- E-axle for rigid truck
- TMS development for IHB
- Lightweight battery protection
- Megacasting part for undercab
- No joggle for BEV platform

Applicable  
for all  
BEV

- Lower cab location
- Air Tube Cross
- Fully aluminum RUP
- Electromechanical brake (airless vehicle system)
- Opportunity for patents and papers

Know  
How for  
all Trucks



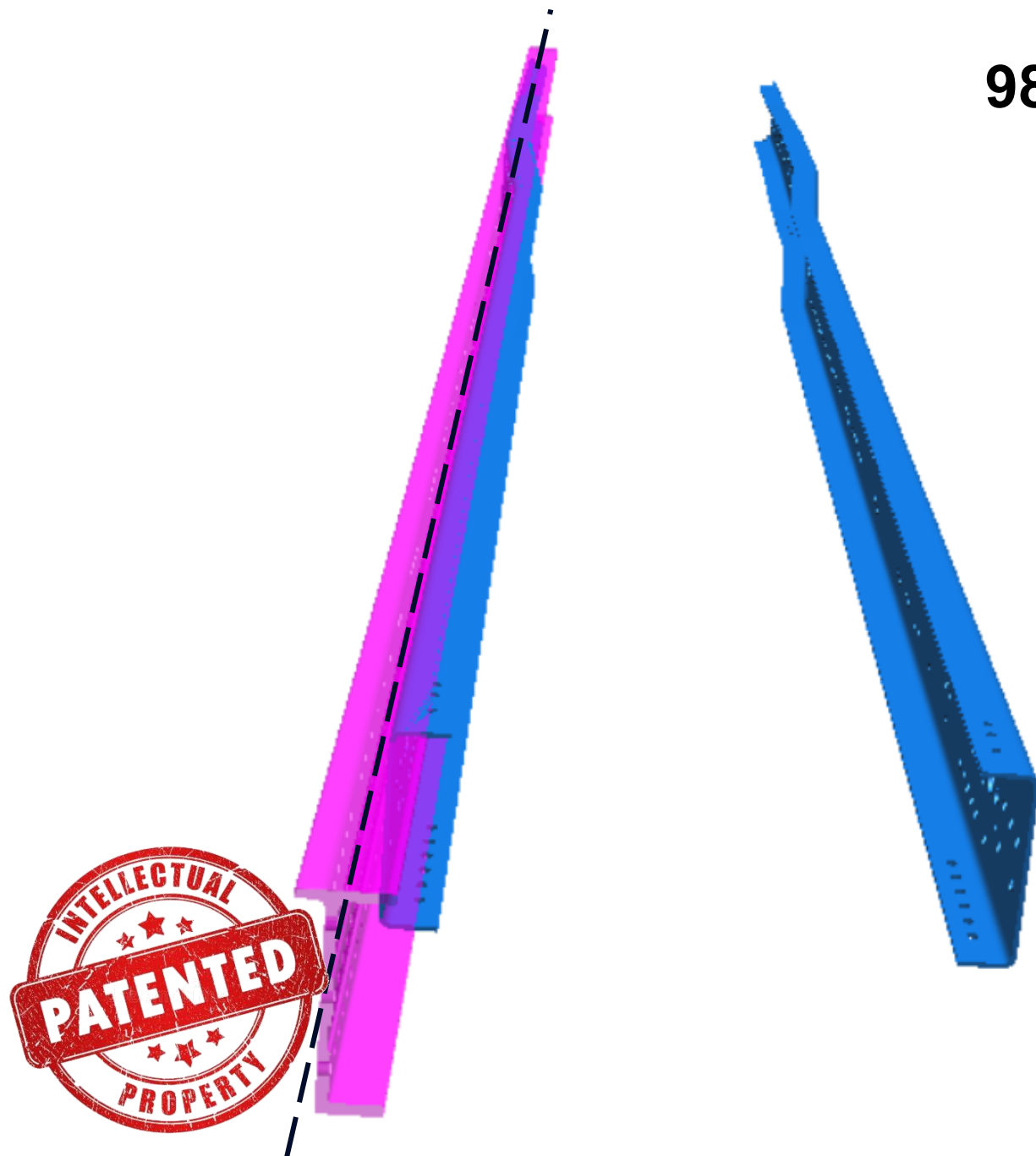
Development of **Expertise** and **Specifications** for a Dedicated Electric Platform



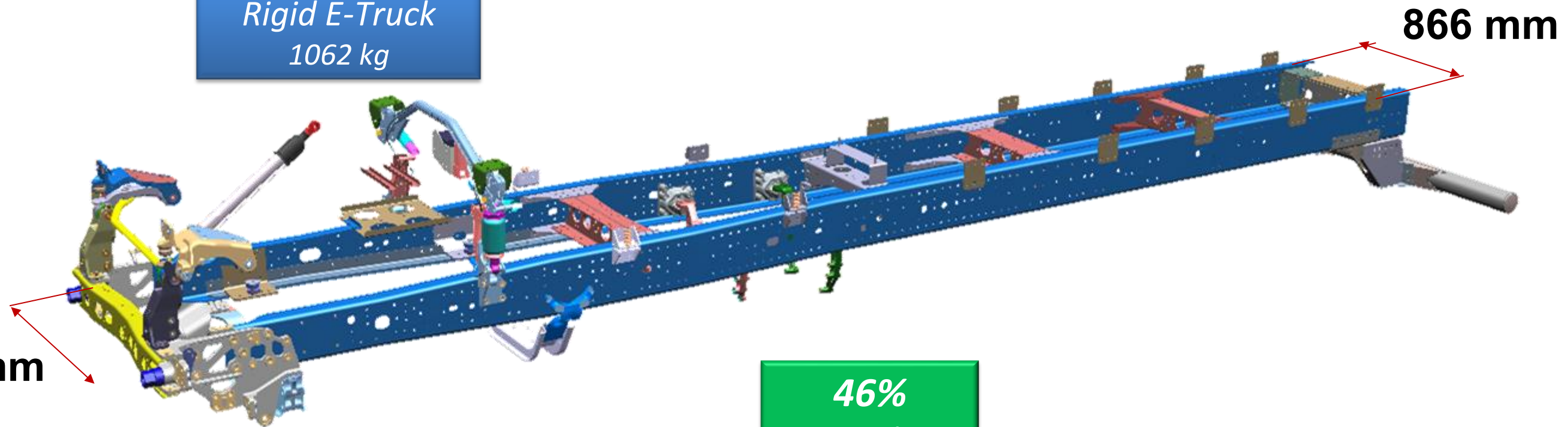
# LADDER FRAME

All frame components are changed

- Lightweight, and modular ladder frame
- Ordered hole pattern on side members

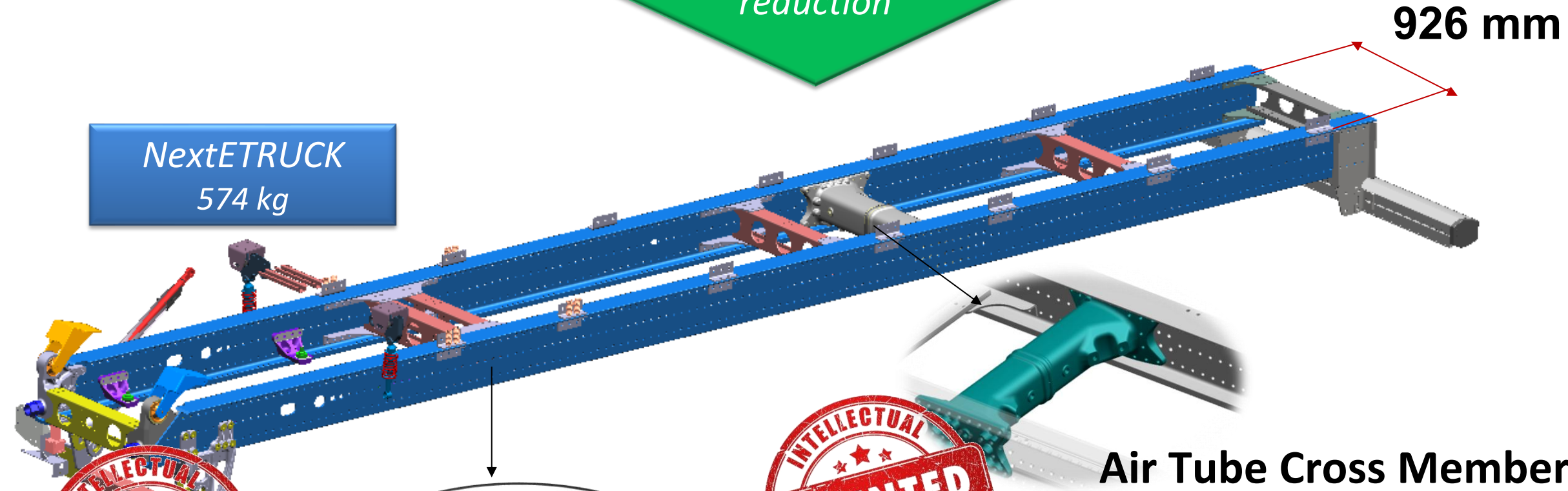


Rigid E-Truck  
1062 kg



46%  
weight  
reduction

NextETRUCK  
574 kg



Intellectual Property Patented

Intellectual Property Patented

**Air Tube Cross Member**

- 20 litre air volume
- Package gain + Torsional stiffness increase



# LADDER FRAME - TESTING

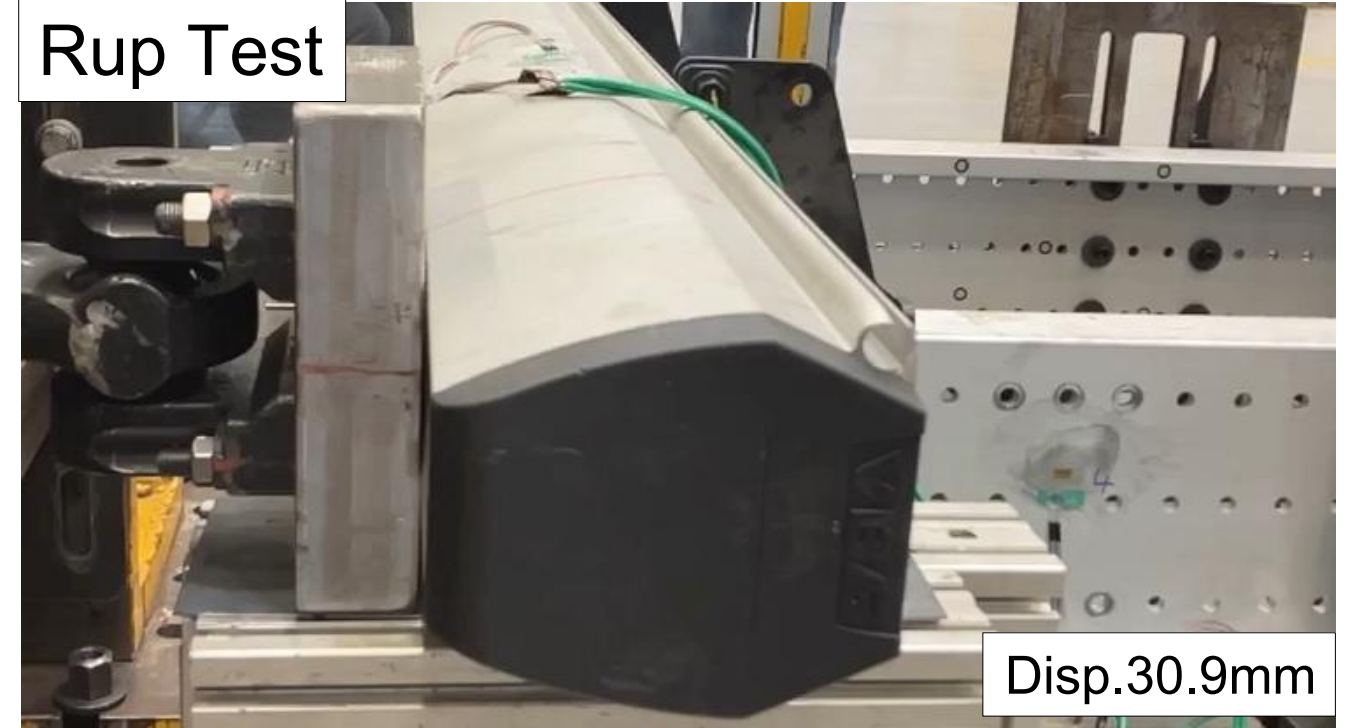
Torsional&Bending Stiffness Test



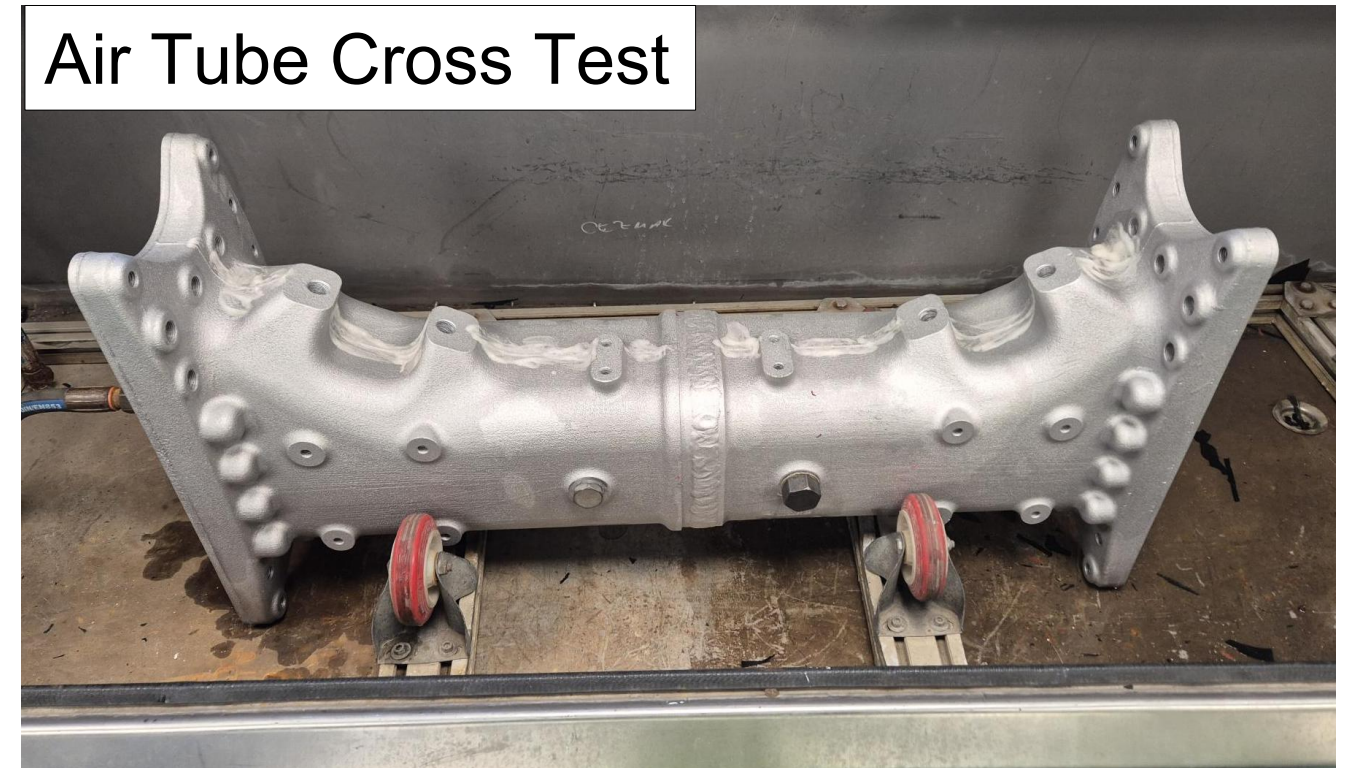
	Test	CAE
Torsional Stiffness	80.84 kNm/rad	79.20 kNm/rad
Bending Stiffness	4.14 kN/mm	4.15 kN/mm



Rup Test

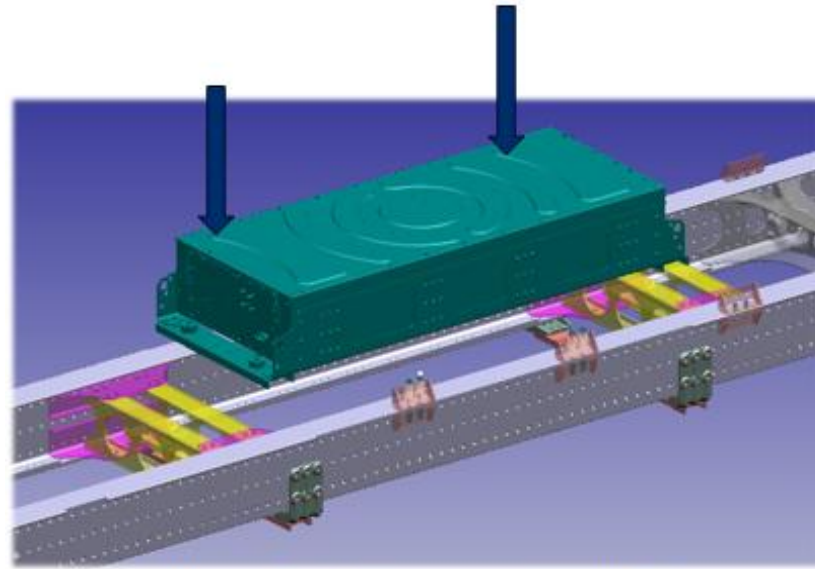


Air Tube Cross Test

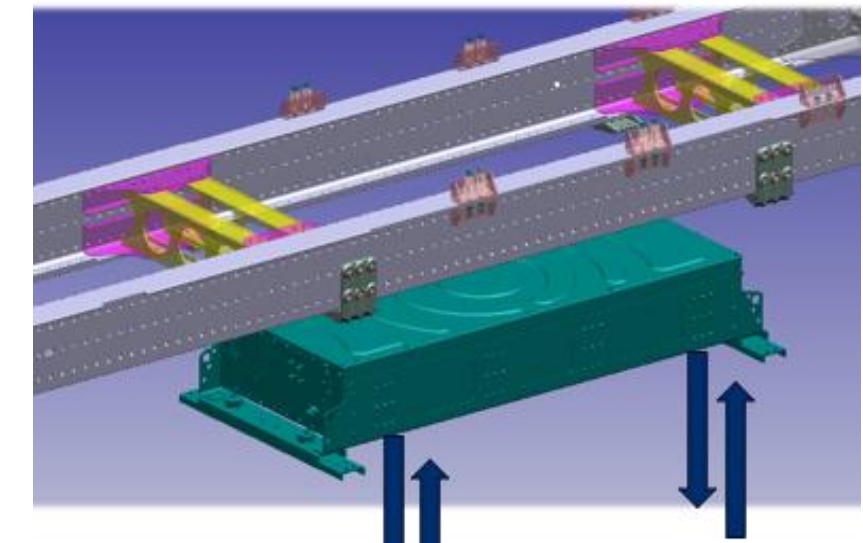
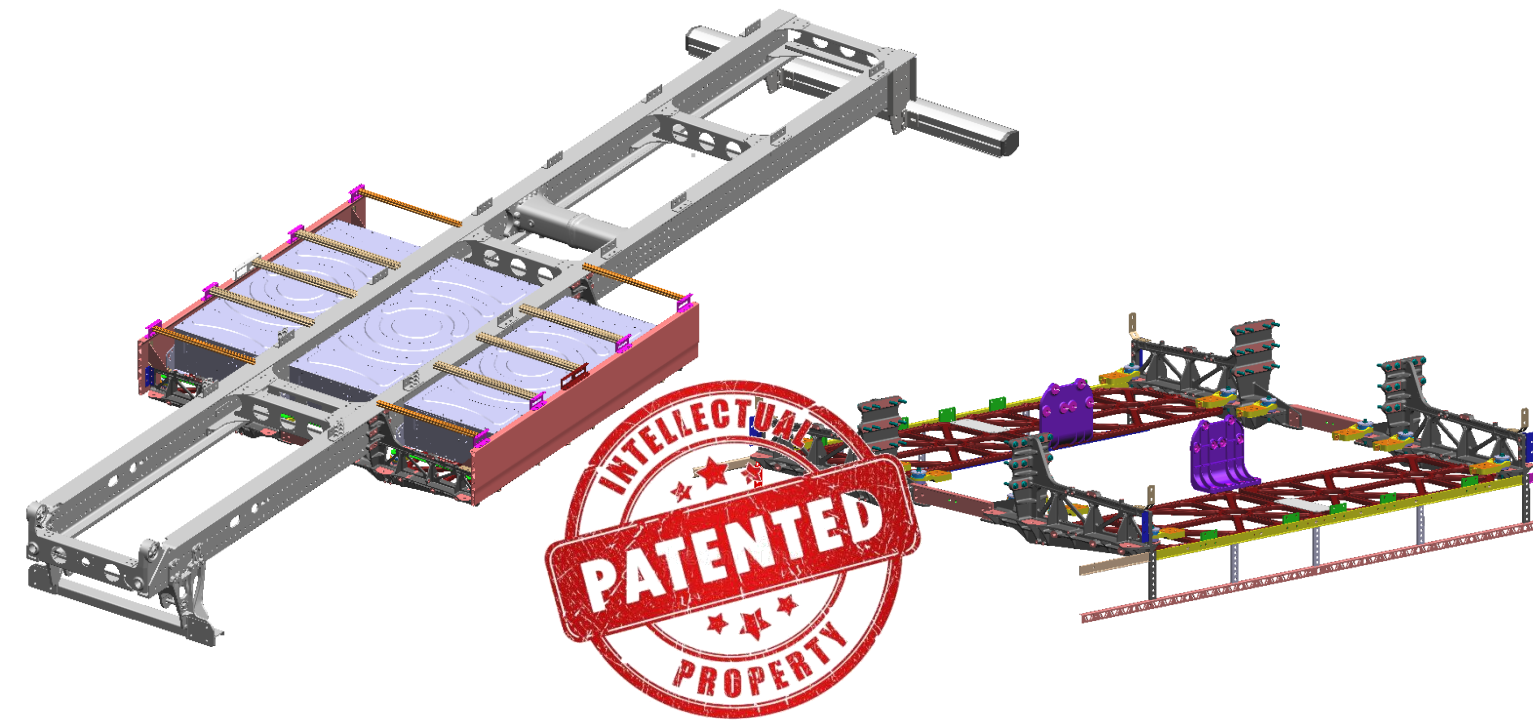




# Battery Location & Serviceability

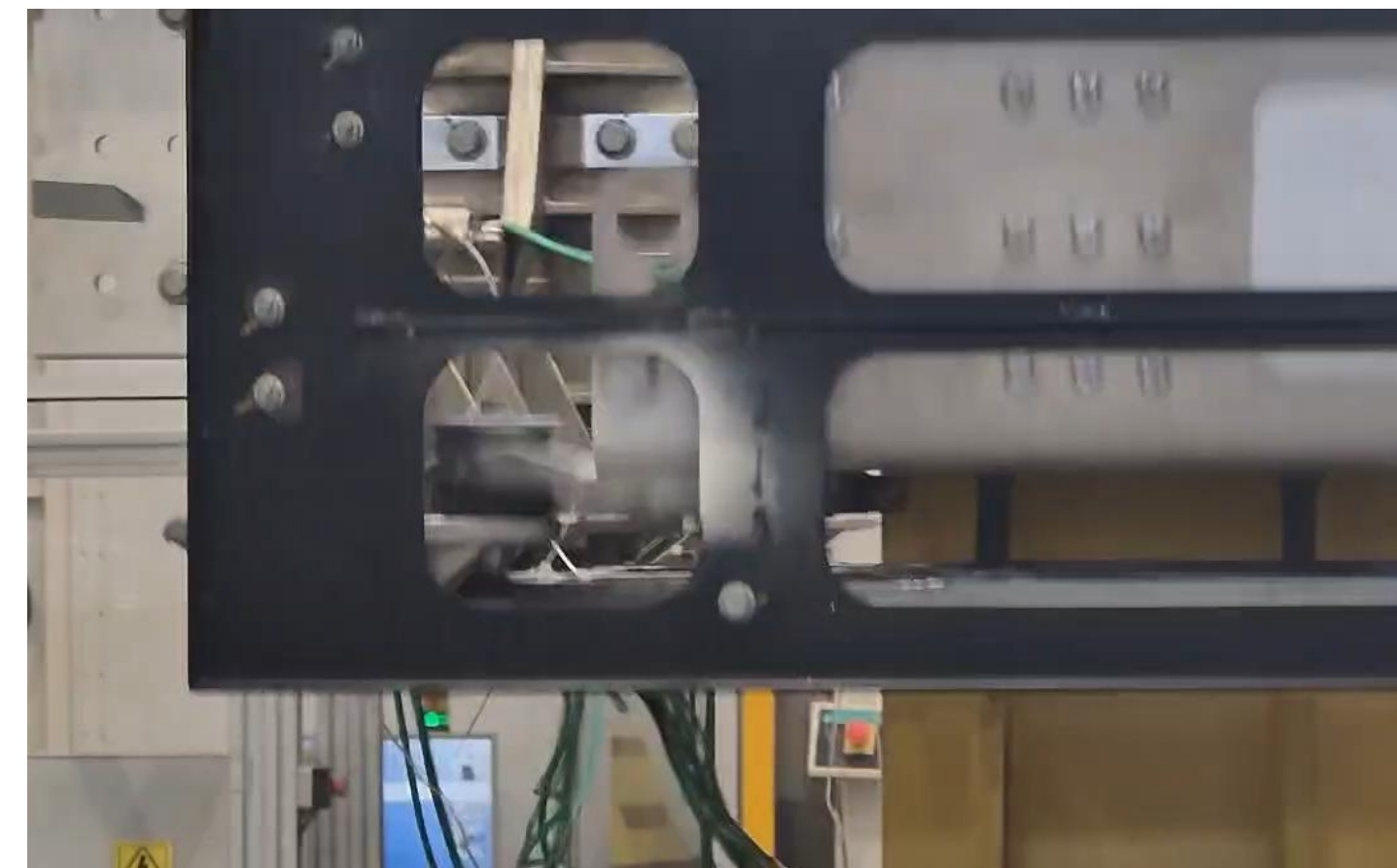
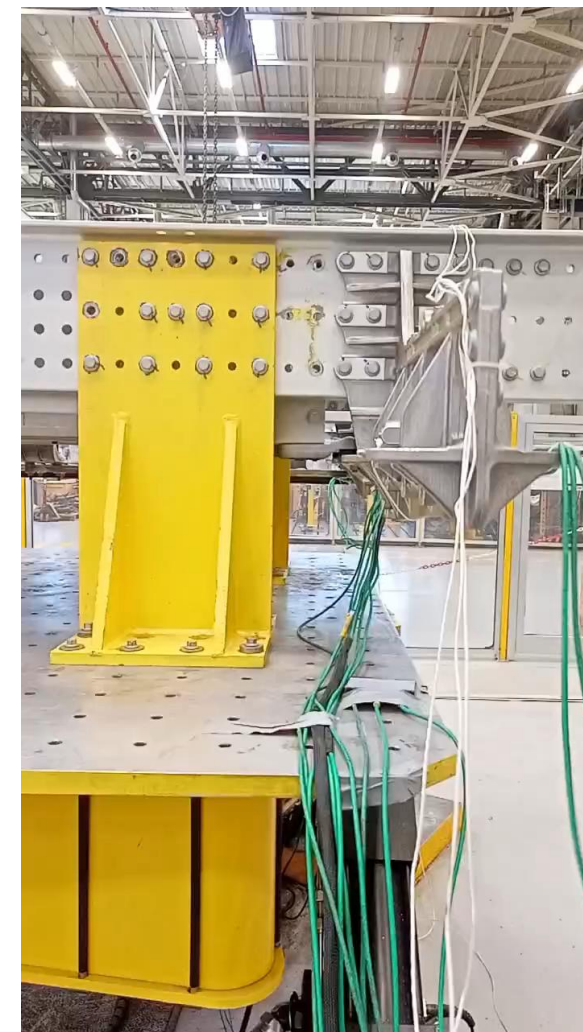


Battery decking on vehicle line from the top of the chassis.



Battery decking at service usage from the bottom of the chassis

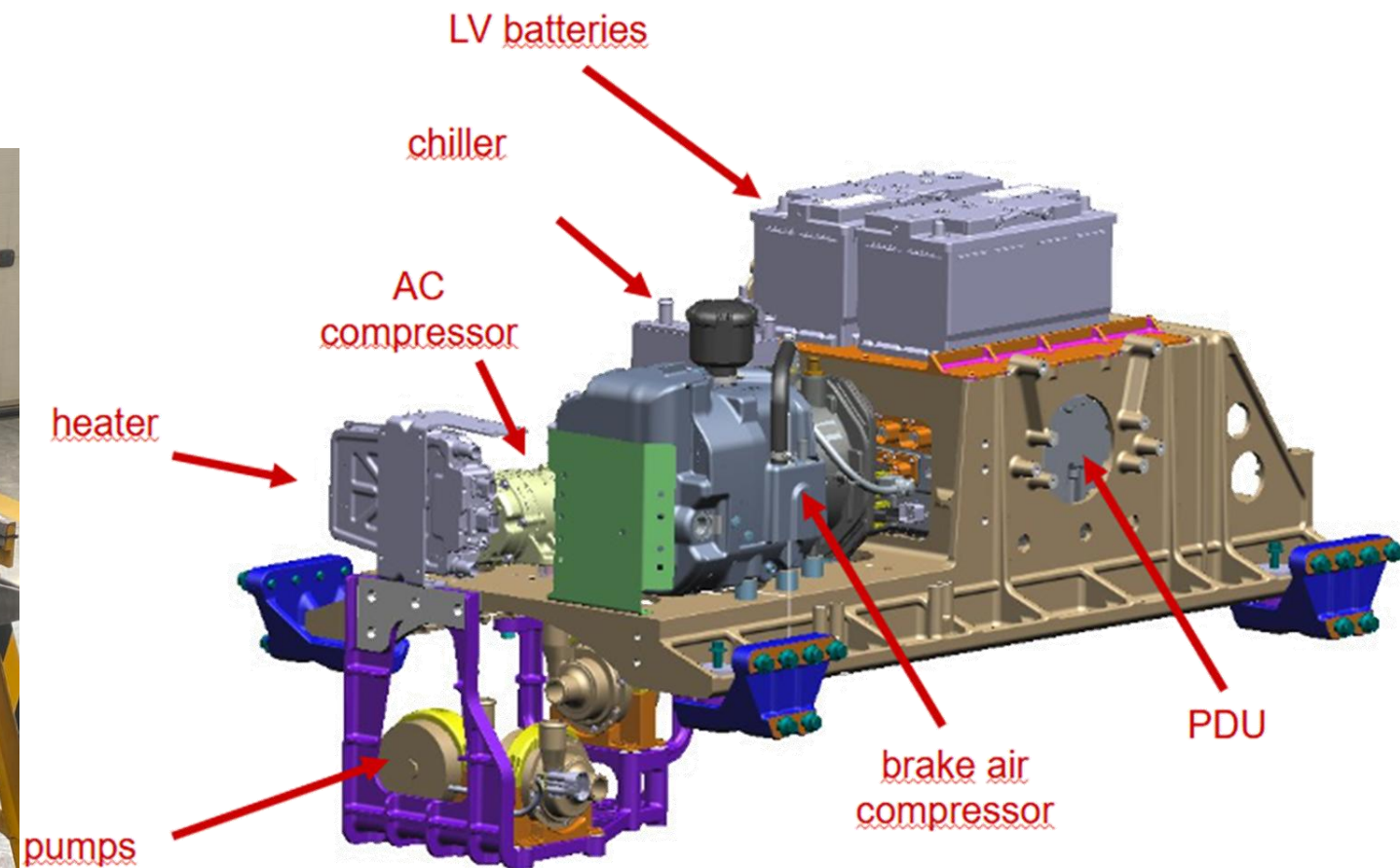
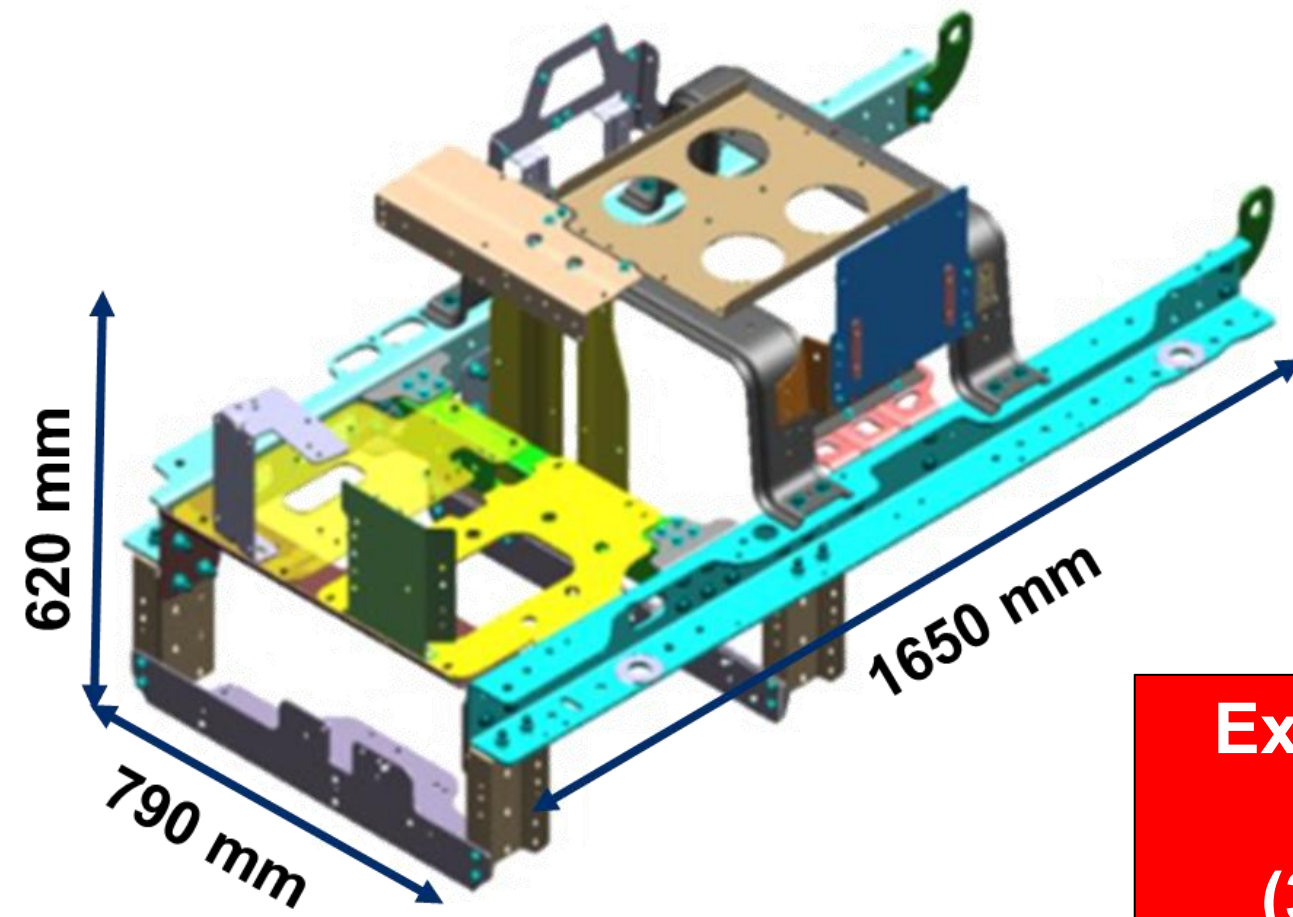
## Test & Validation



Tests are conducted for CAE correlation.



# Mega-Cast Undercab Carrier:



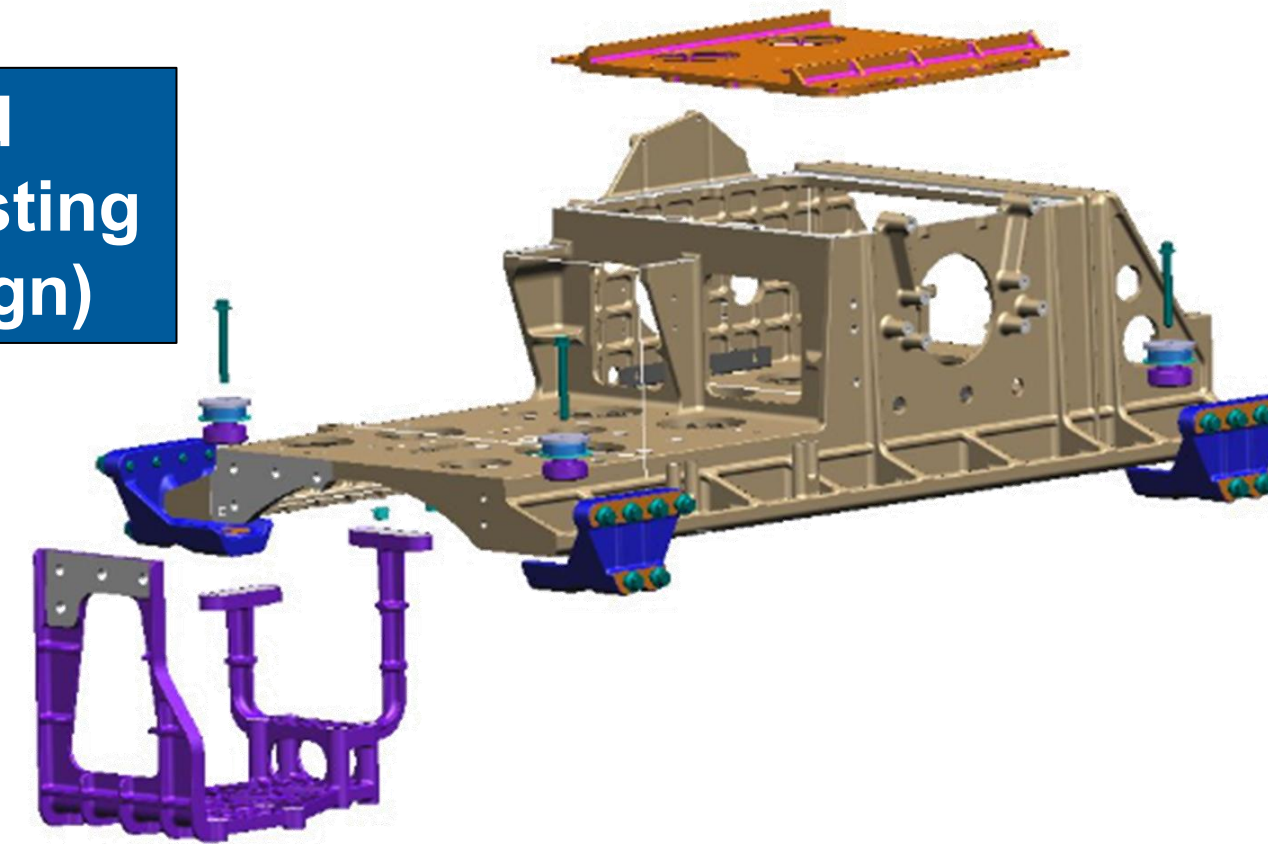
**Existing Steel Design**  
161 kg  
(33-part assembly)

**3D Sand-Printed Aluminum Giga-Casting**  
66 kg (3-part design)

*The under-cab carrier system is designed to carry electric vehicle systems with a total weight of approximately 150 kg.*

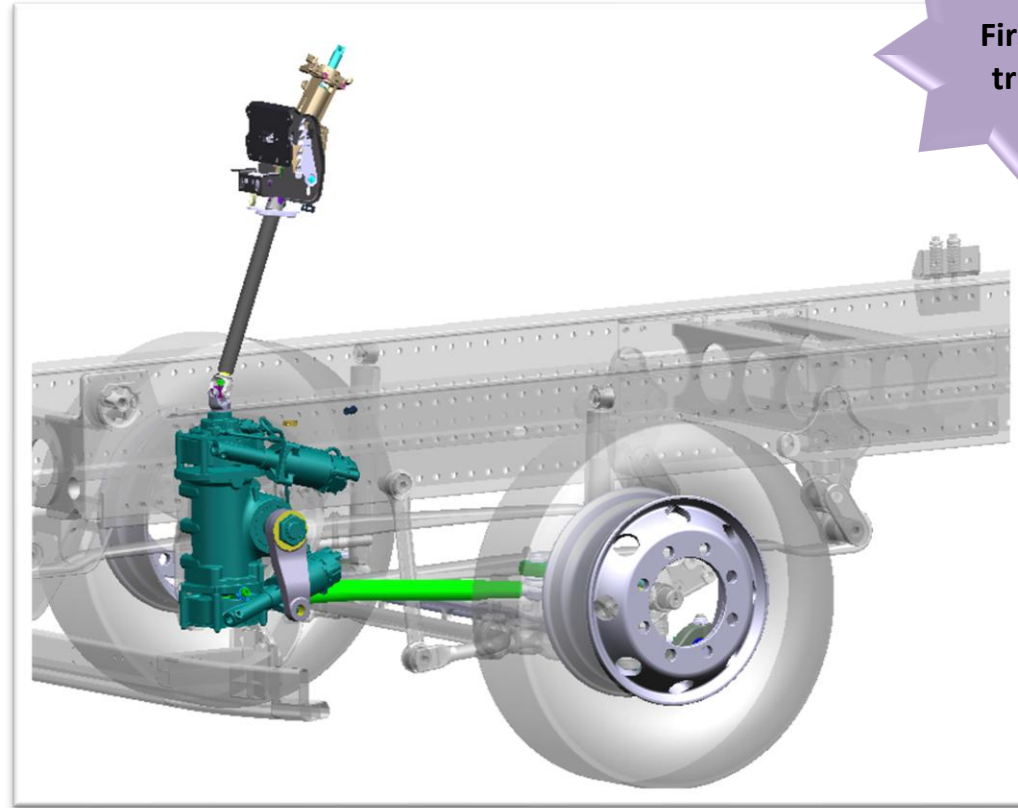


**60 % Weight Reduction (95 kg)**





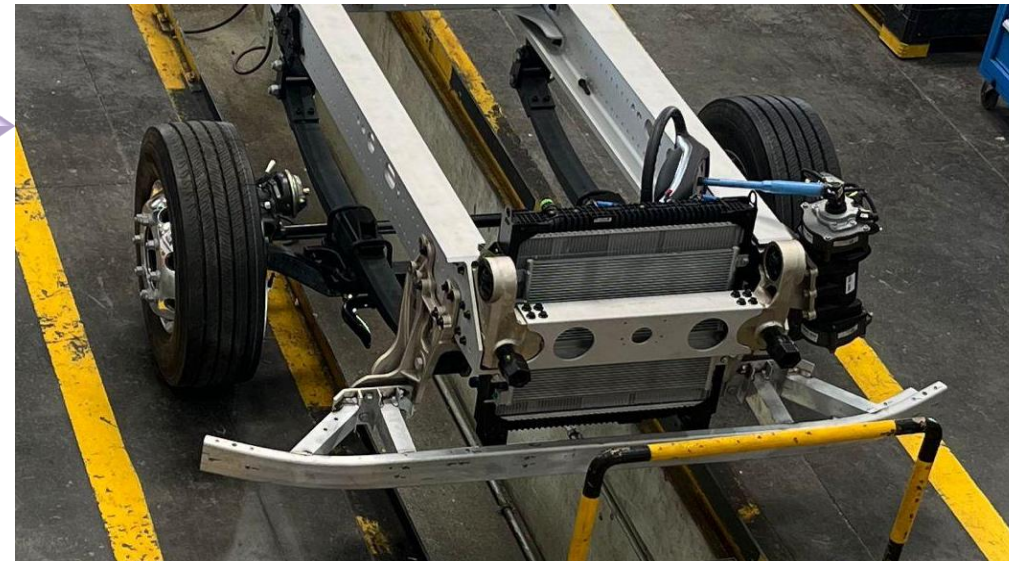
# Steering & WTJ



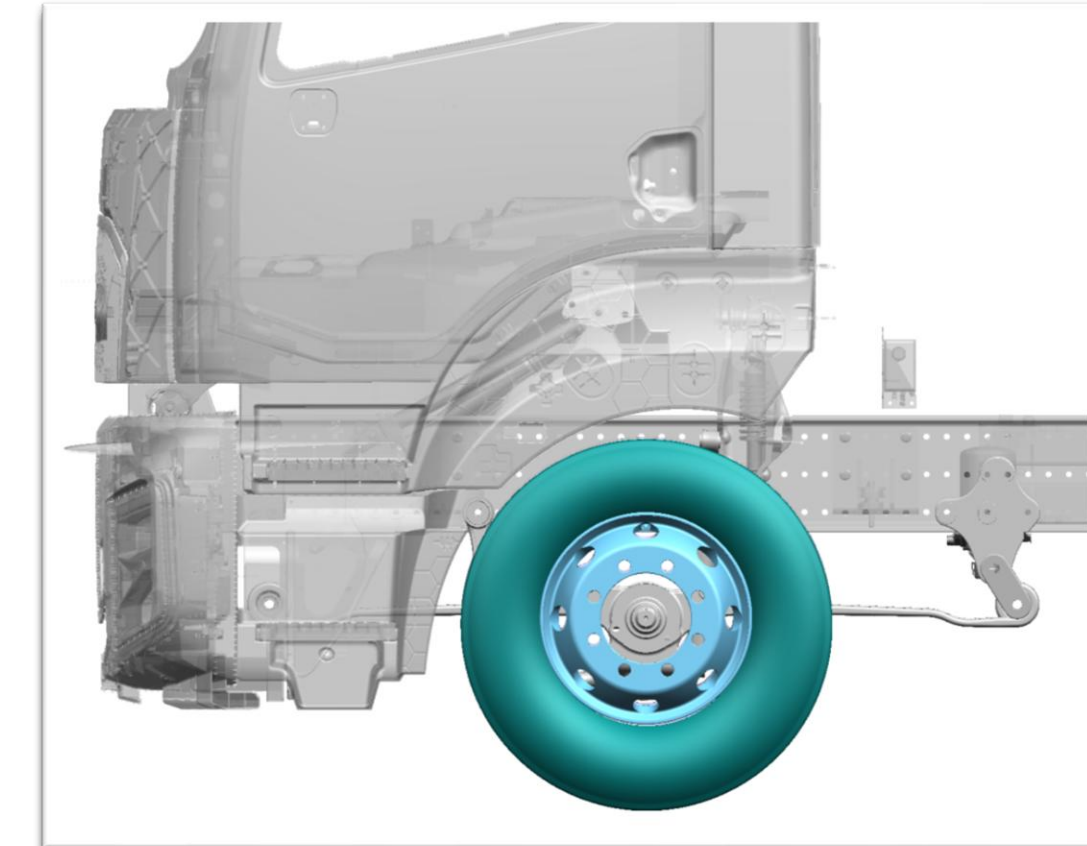
First in truck

## EPS

- No hydraulic support needed.
- Supports fully autonomous drive (L4).
- High efficiency >%82 savings vs. EHPAS.



- Plug & Play component
- No oil in assembly line
- No additional e-pump required in BEV/FCEV
- Power on Demand component
- Better overall efficiency
- Emergency Steering Support
- Steer-by-wire applicable
- Level 4 Automation ready
- Extremely low free play and excellent steering feel



## 19,5 inch wheels and tyre

- Aluminum rim
- Lighter system
- Lower SLR

↓ 171 kg Weight Reduction

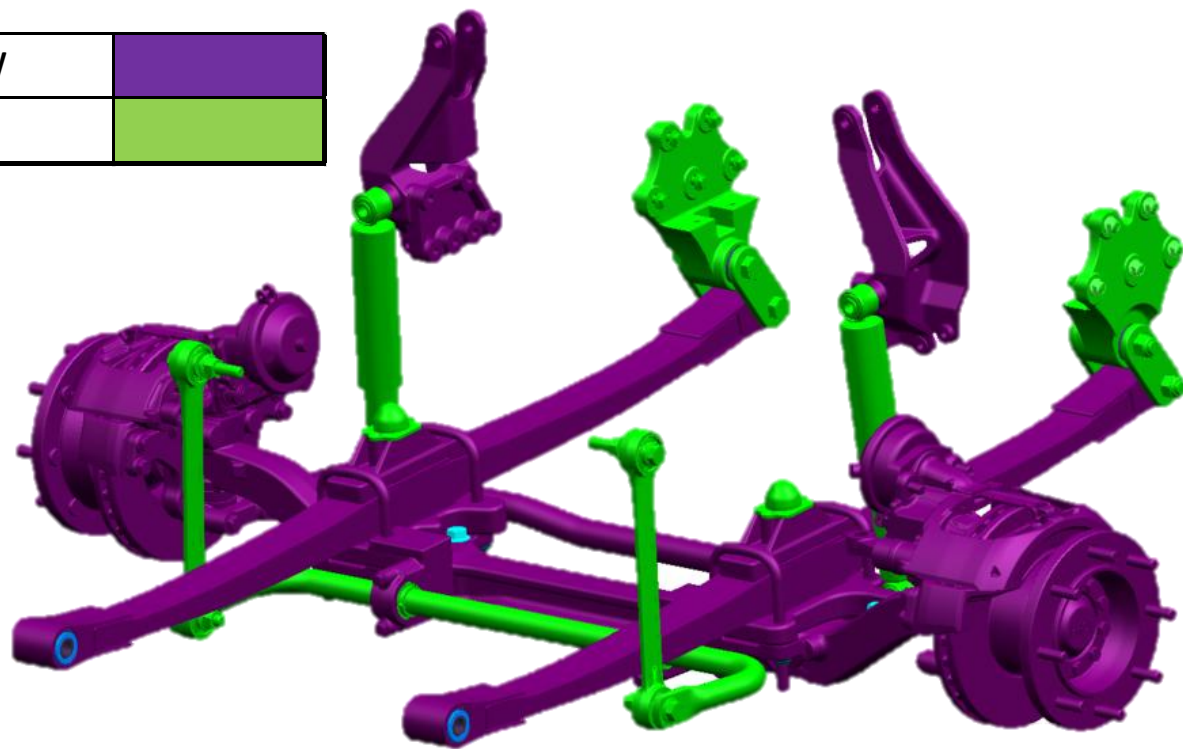
↓ 90mm Lower SLR





# Front Suspension system

NEW	
C/O	



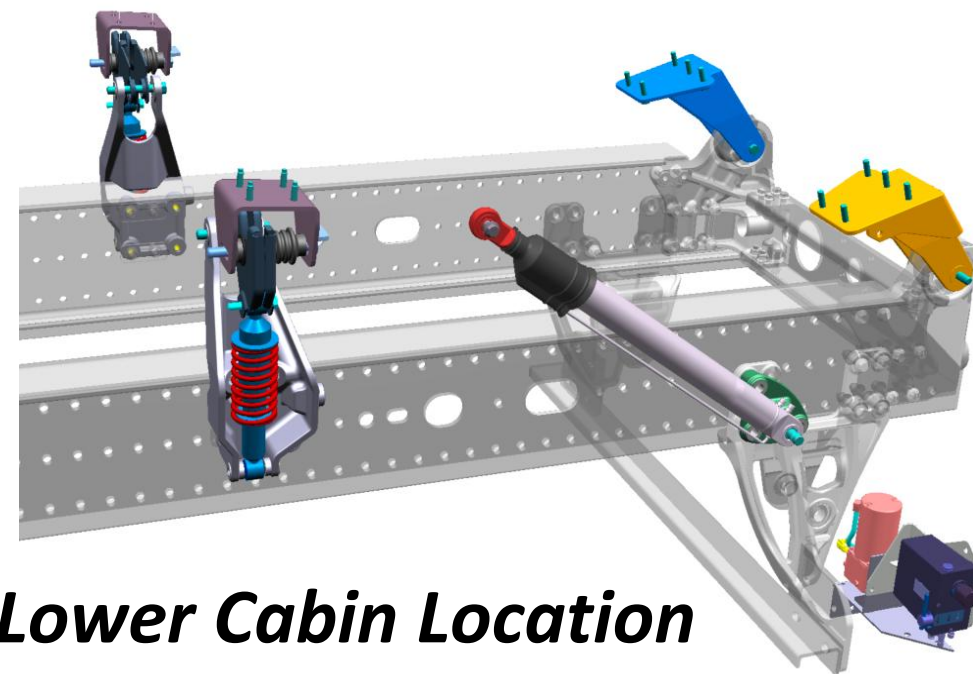
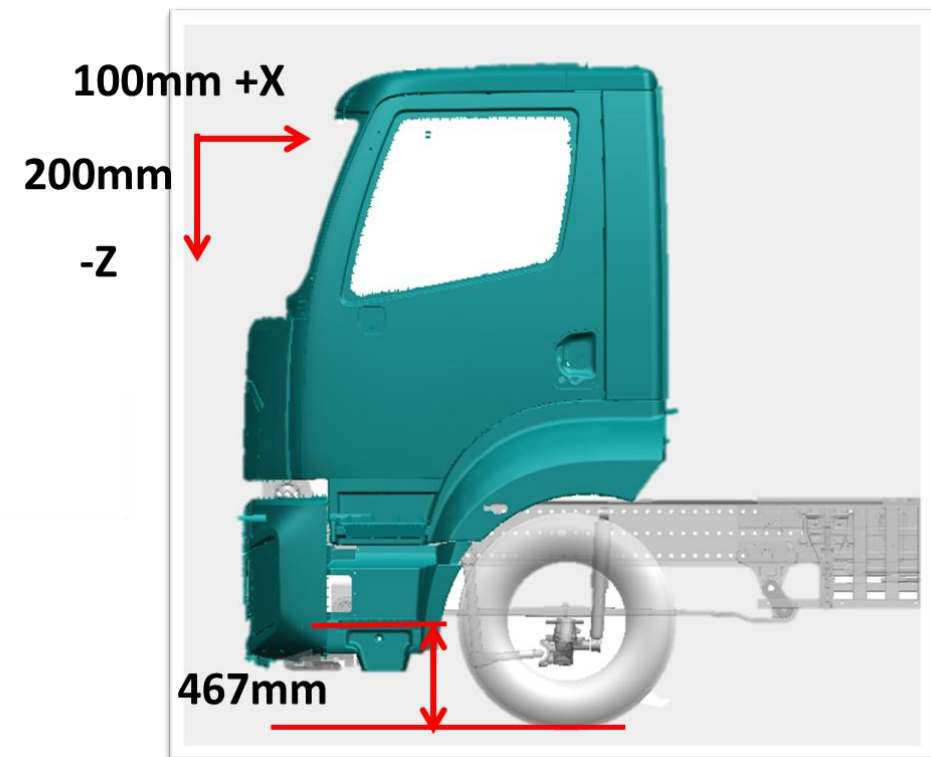
- Significantly lighter **composite monoleaf springs**
- 19" rim-compatible off-the-shelf axle subsystem (incl. braking & steering)
- Significantly **lighter aluminum hub** — among the first in the European market



System	Weight
Current Frt Susp.	480 kg
Next e-Truck Frt Susp.	370.2 kg

Total: 109,8 kg WR

# CAB Suspension System

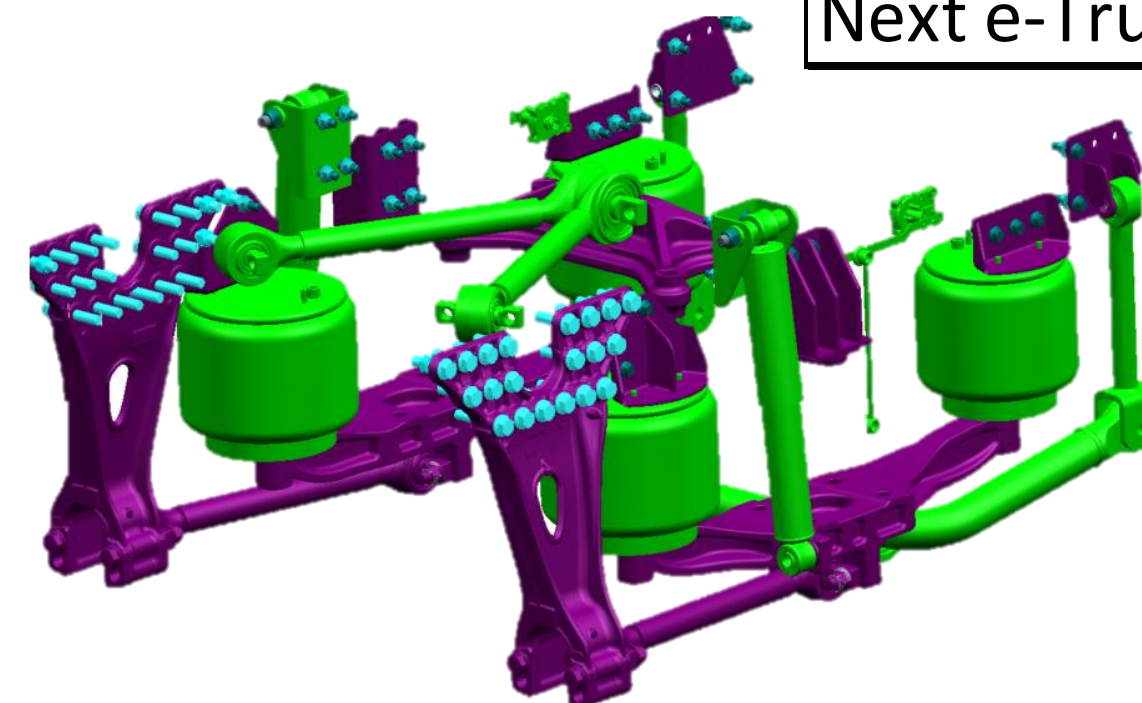


## Lower Cabin Location

- Better driver vision
- Easier to get on the truck
- 467mm first step height

# Rear Suspension System

NEW	
C/O	



System	Weight
Current C4AS	322,7 kg
Next e-Truck C4AS	294,6 kg

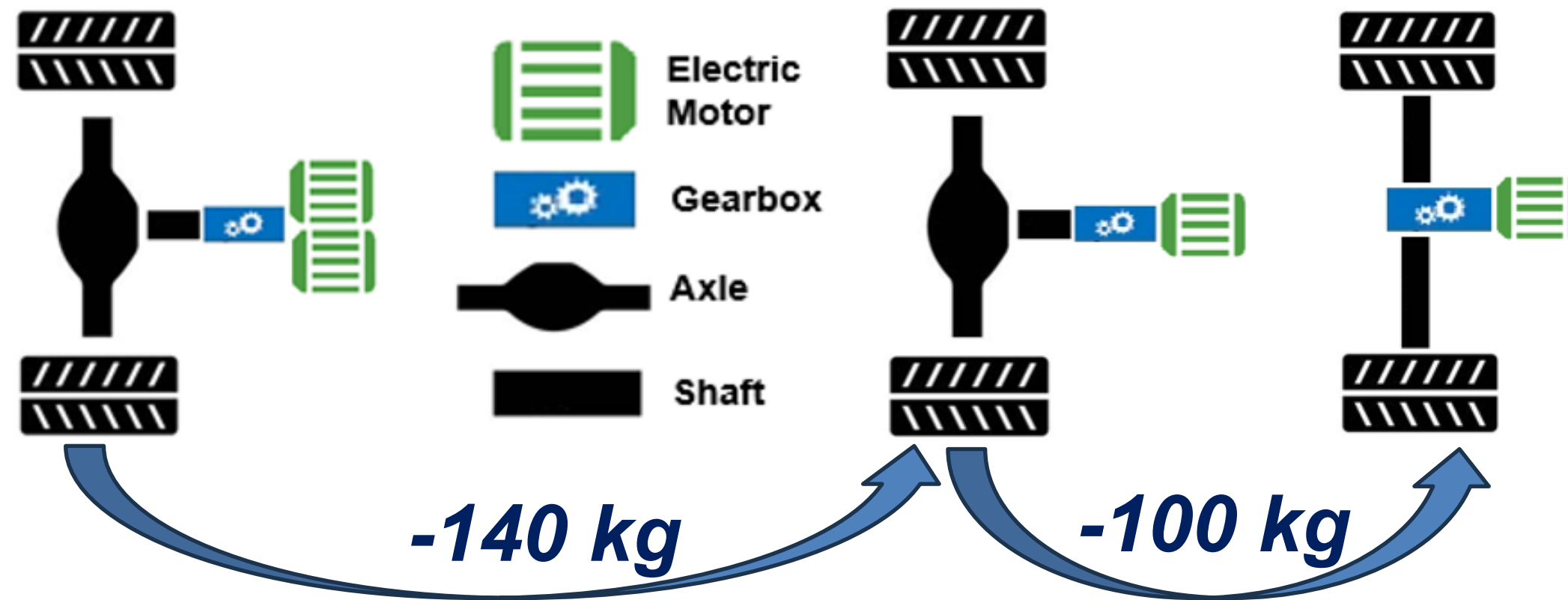
Total: 28,1 kg WR



# POWERTRAIN STUDIES



19T Baseline Vehicle



16T NextETRUCK

- Powertrain concept optimization (from dual- to single-motor) → 140 kg weight reduction
- Further eDrive system simplification with e-axle → additional 100 kg weight reduction
- 19.5" e-axle architecture (vs. 22.5"), among the first in the market → additional weight savings in brake and wheel-rim systems



# CABIN ARCHITECTURE

VA support is provided internally by the LCV Trim & Body Design Team.

## Relocated Cabin Position

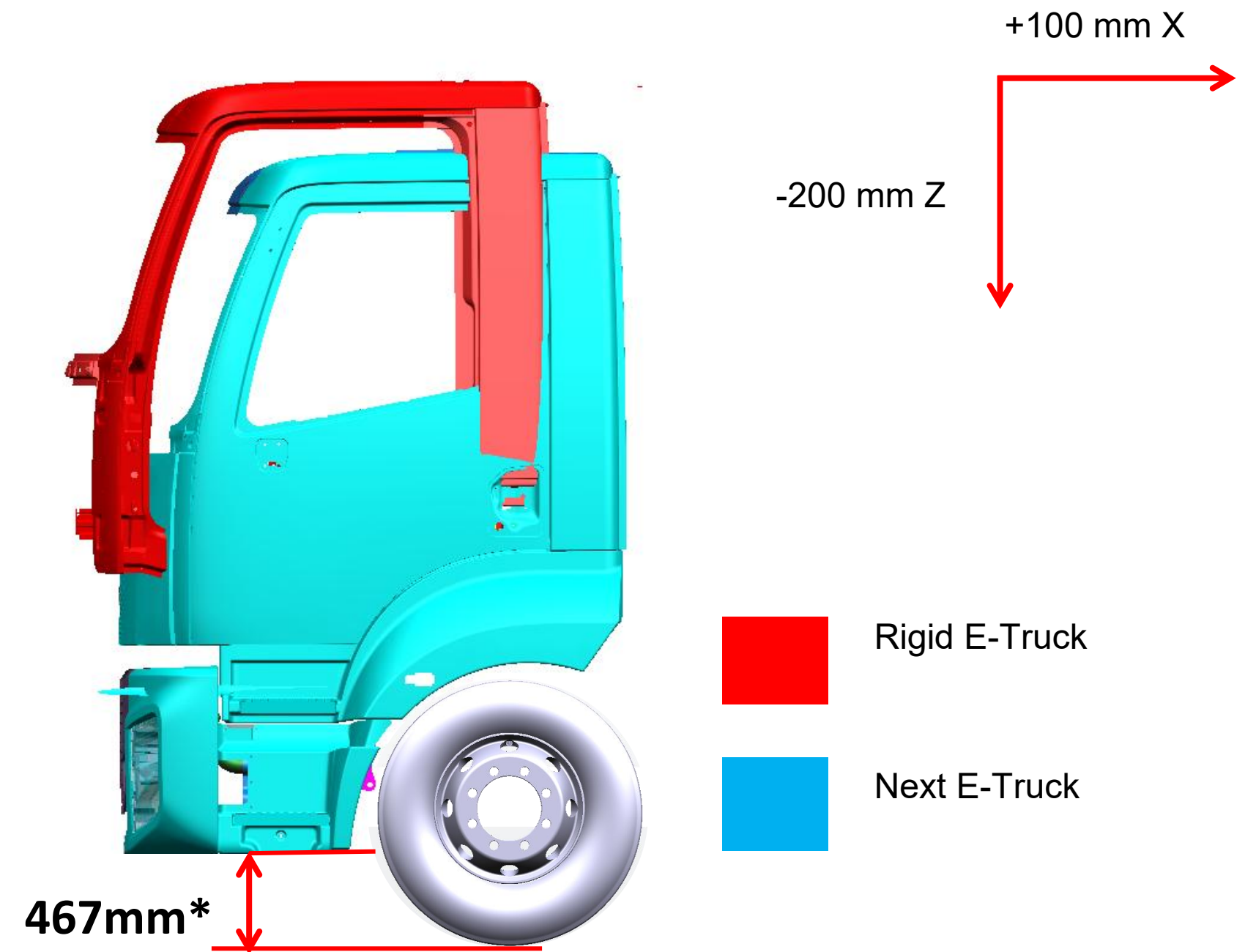
Easy entry to the cabin with two side steps and lower position.

Better driver vision especially for urban usage.

Improved aero performance

Construction short bumper implementation on road truck for better ground clearance

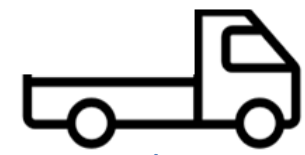
With R19,5 Wheel size usage (First time in Truck projects), 467mm first step height can be achieved.



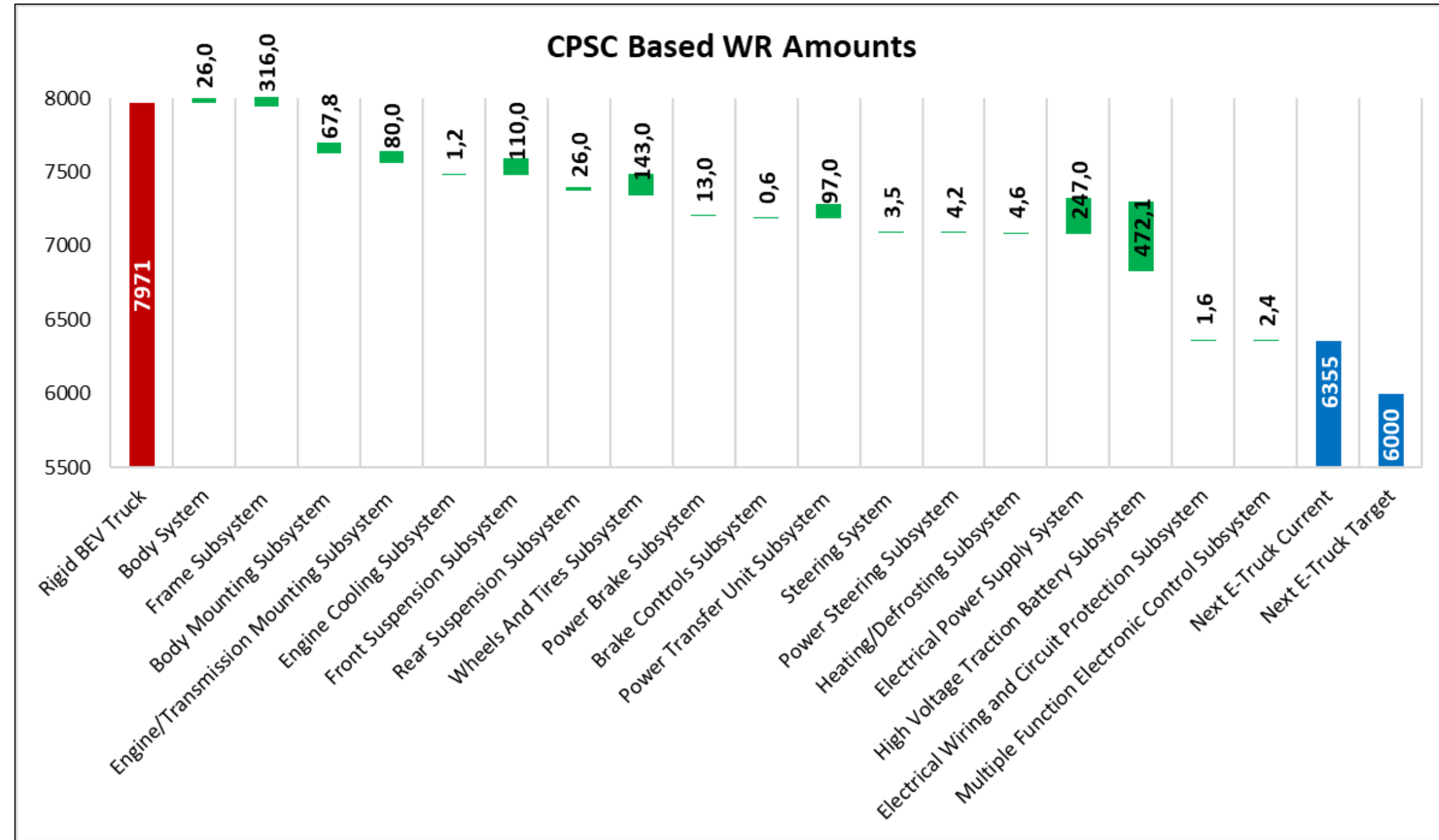
Improved accessibility: first step height reduced to 467 mm via optimized cabin layout and smaller tires



# WEIGHT STATUS



	BKW 1.Axle (kg)	BKW 2.Axle (kg)	BKW Total (kg)	GVM Total
Rigid BEV Truck	4790	3181	7971	19000
Next E-Truck	3360	2578	<u>5938</u>	16000



Achieved weight reduction is 1607 kg



# NextETRUCK : Build of Vehicle



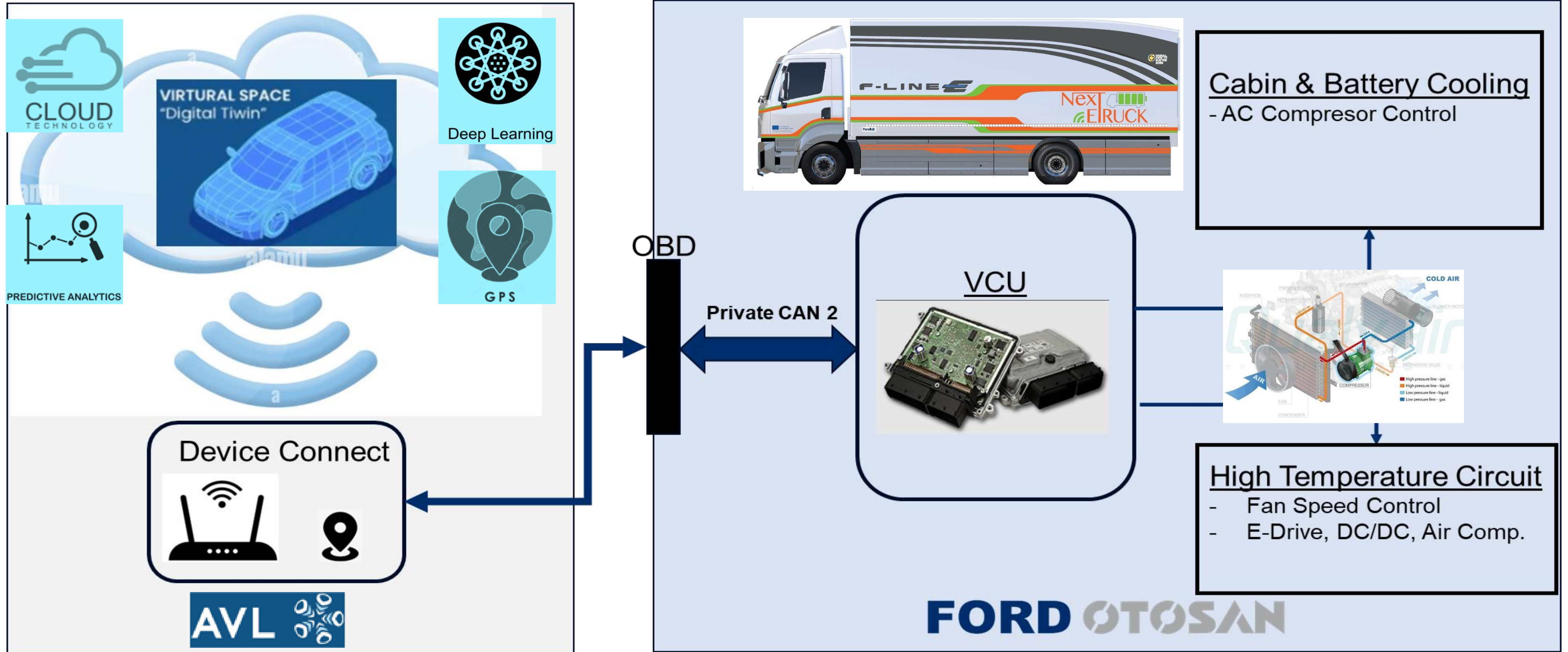


# Digital Twin Description and Pre-Studies





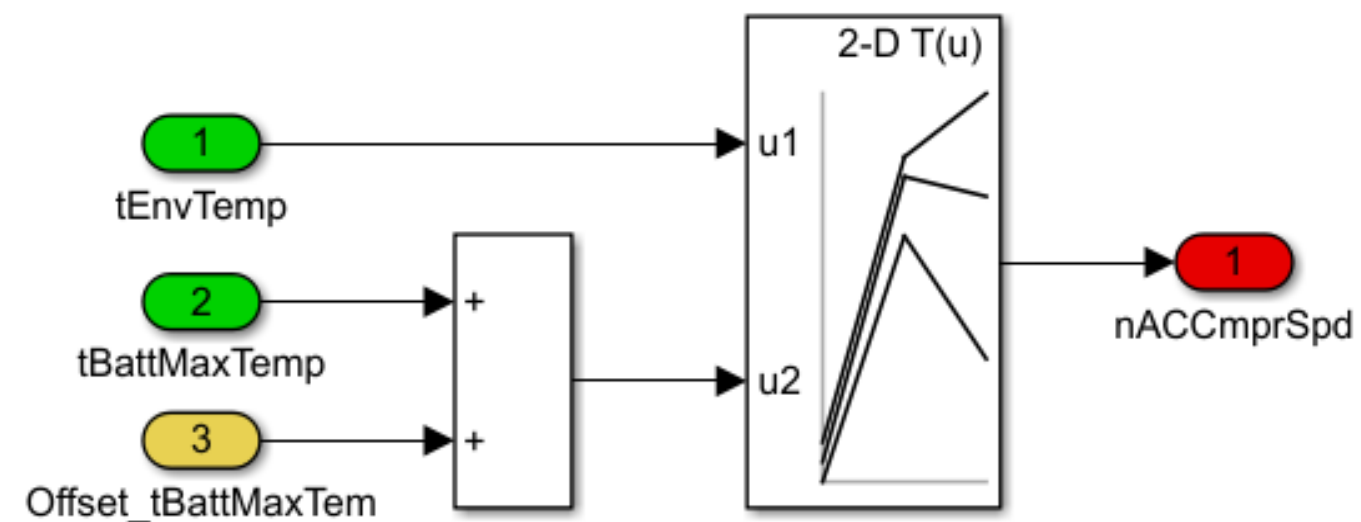
# Digital Twin: Vehicle Application Layout





# Setpoints and Signal Definitions

- Digital Twin model optimizes fan and compressor control in e-trucks by integrating real-time and cloud-based thermal signals.
- Offset adjustments enhance cooling decisions, ensuring efficient and intelligent control.



- This approach reduces energy consumption, improves thermal stability, and extends system longevity.

## From Cloud to VCU

- Set temperature of coolant at powertrain inlet
- Set temperature of coolant at battery temperature
- Connection Check value DT

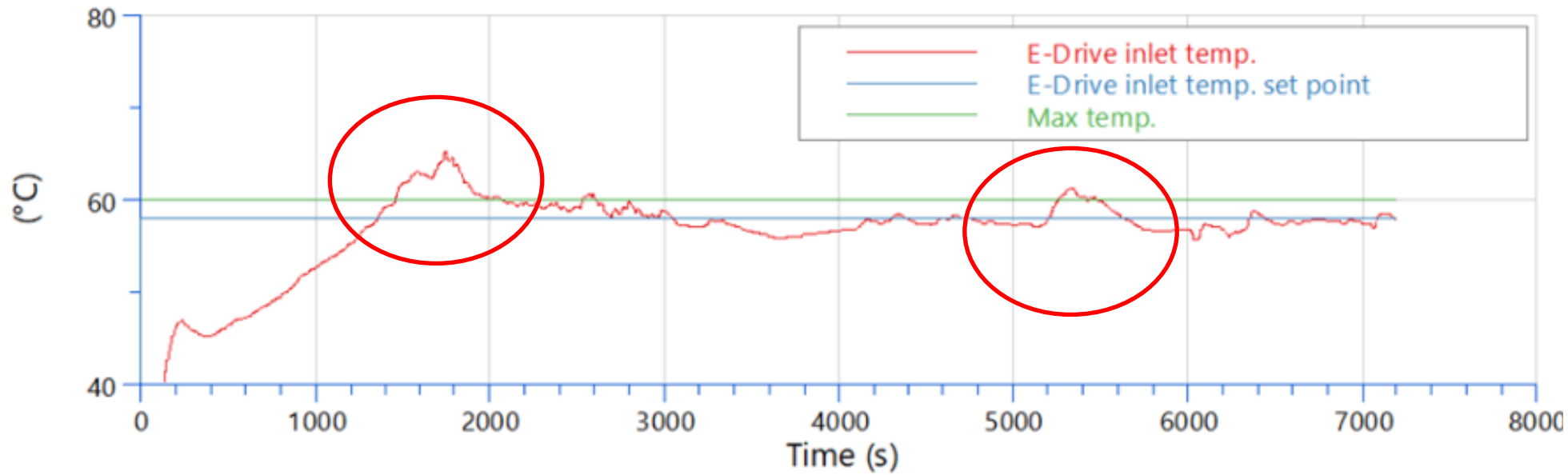
## From VCU to Cloud

- Connection Check value Truck
- Cloud connection established
- Actual vehicle speed
- Vehicle slope
- Vehicle total weight
- Battery SoH
- Battery SoC or SoE
- Battery current
- Battery voltage
- Actual Ambient temperature
- Cabin temperature Setpoint
- Actual coolant temperature at powertrain inlet
- Actual coolant temperature at battery inlet
- Actual coolant temperature at battery outlet
- Actual Maximal battery temperature
- Actual Minimal battery temperature

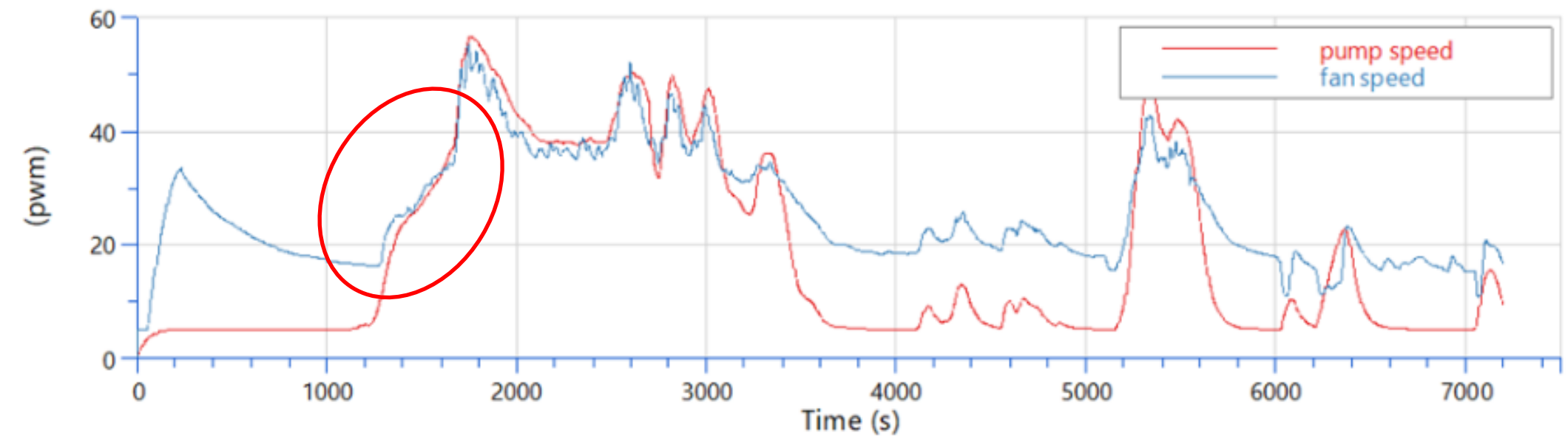
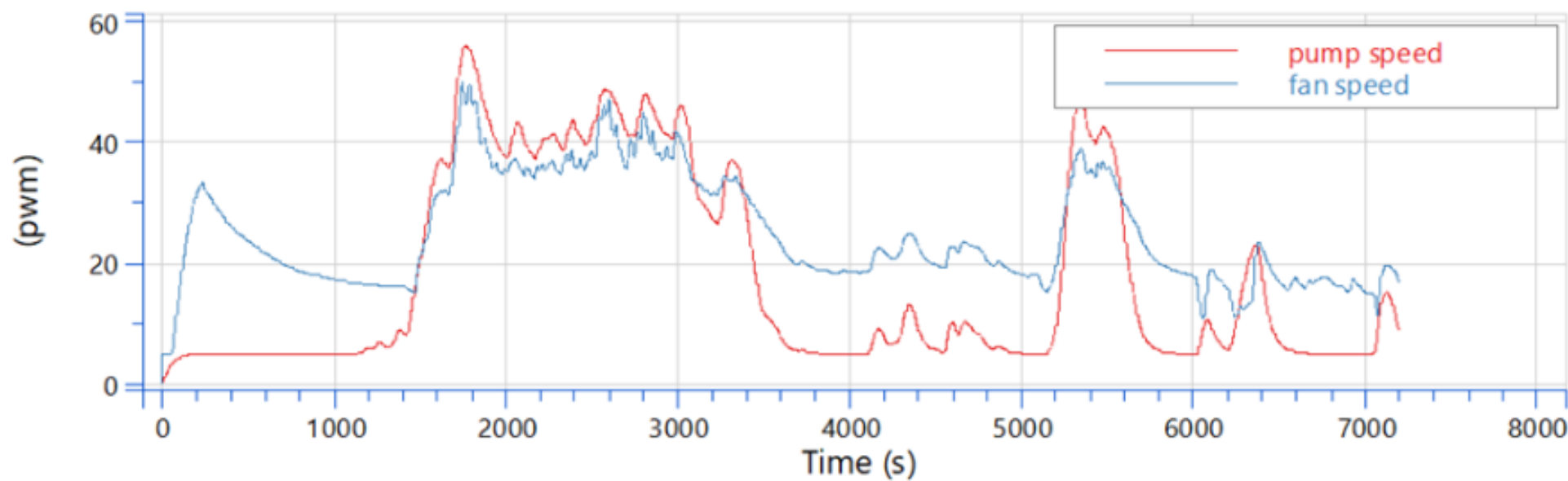
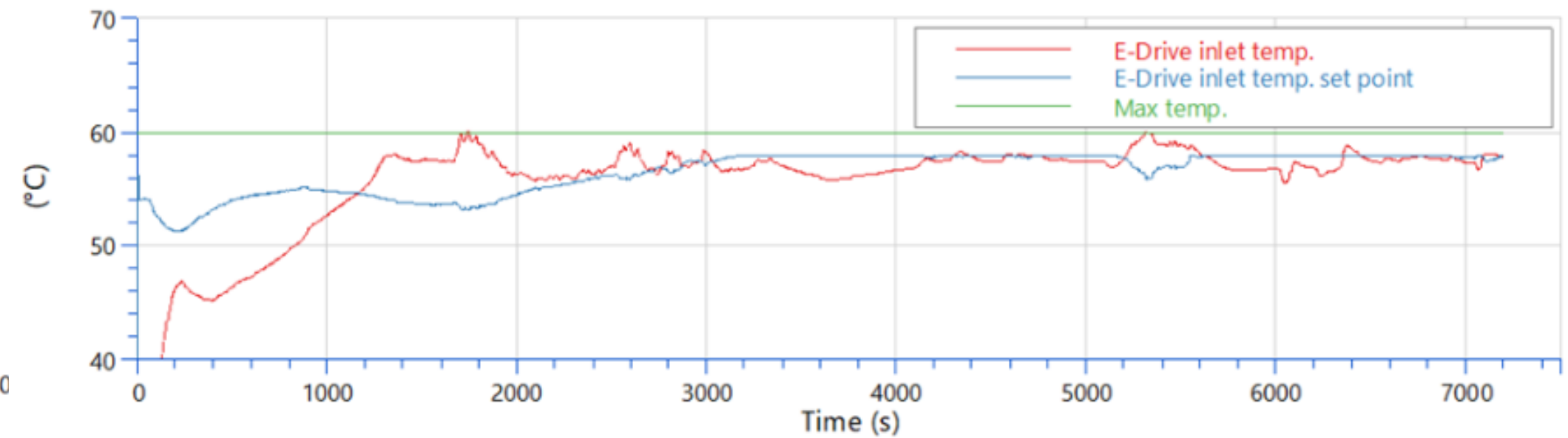


# Comparison of Predictive and Non-Predictive Setpoint

GoEkGo\_V2 cycle at 30 °C with static setpoint of 58 °C



GoEkGo\_V2 cycle at 30 °C with predictive setpoint up to 58 °C



A static setpoint of 58 °C without predictive adjustment leads to the temperature limit being exceeded.



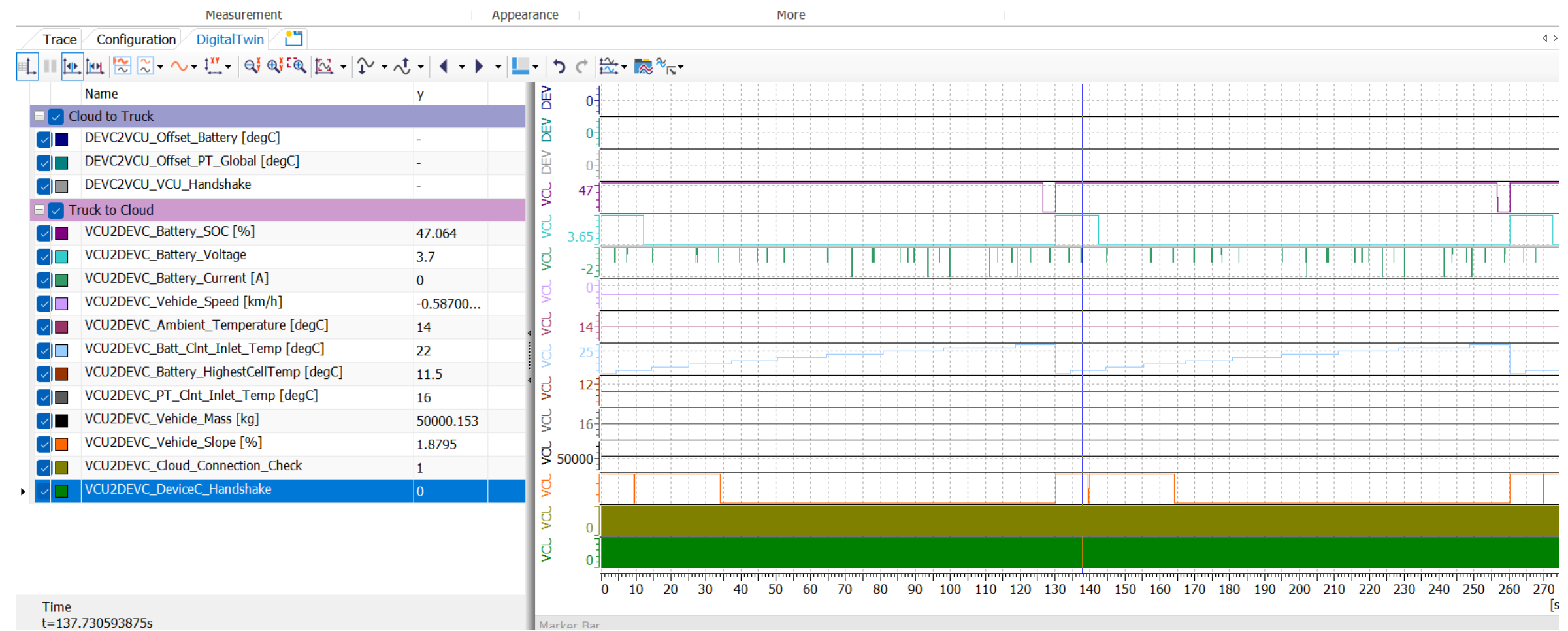
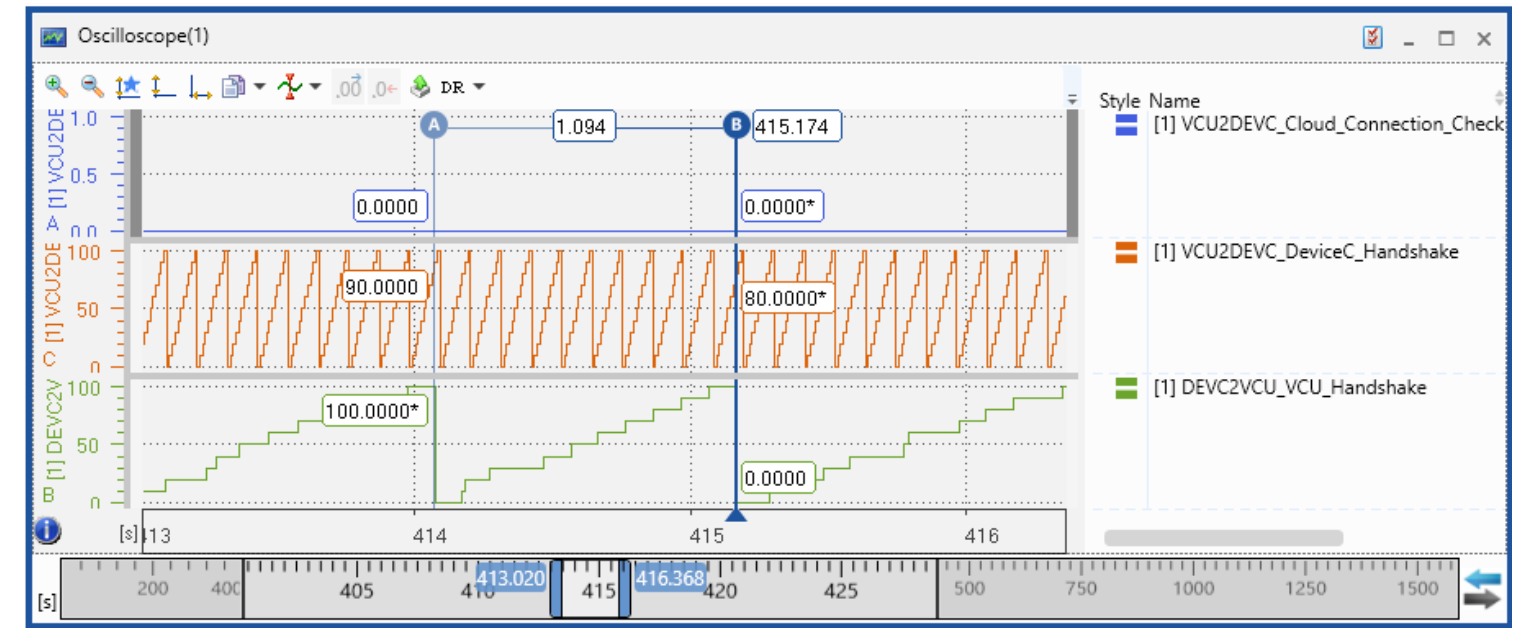
# HIL Testing and Vehicle Application Tests





# HIL Test Bench

- The aim of this study is to power up the Can Connect device on the HIL test bench and verify the successful transmission of signals to the Cloud.
- These tests were carried out in coordination with AVL.





# Calibration Studies

**Platform Variations:**

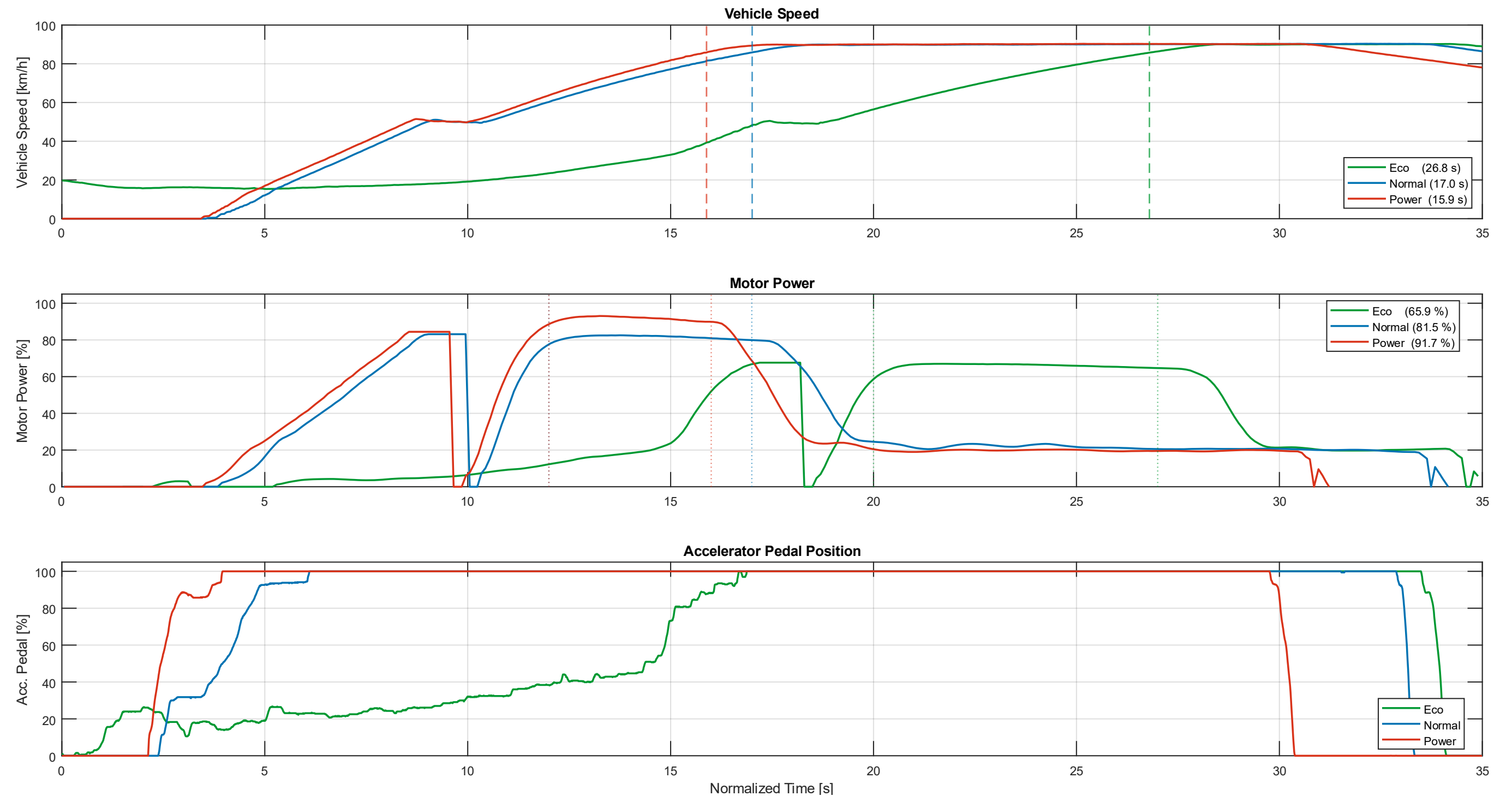
- Motor power: 250 kW
- Gross Vehicle Weight
- Different eDrive (eAxle)

**Calibration Strategy & Outcome:**

- Standardized calibration has been executed
- Relative power targets (65%, 80%, 100%) successfully integrated.

Mode	Desired Power	Actual Power
Eco	65%	65.9%
Normal	80%	81.5%
Power	100%	91.7%

NeT Drive Mode Comparison

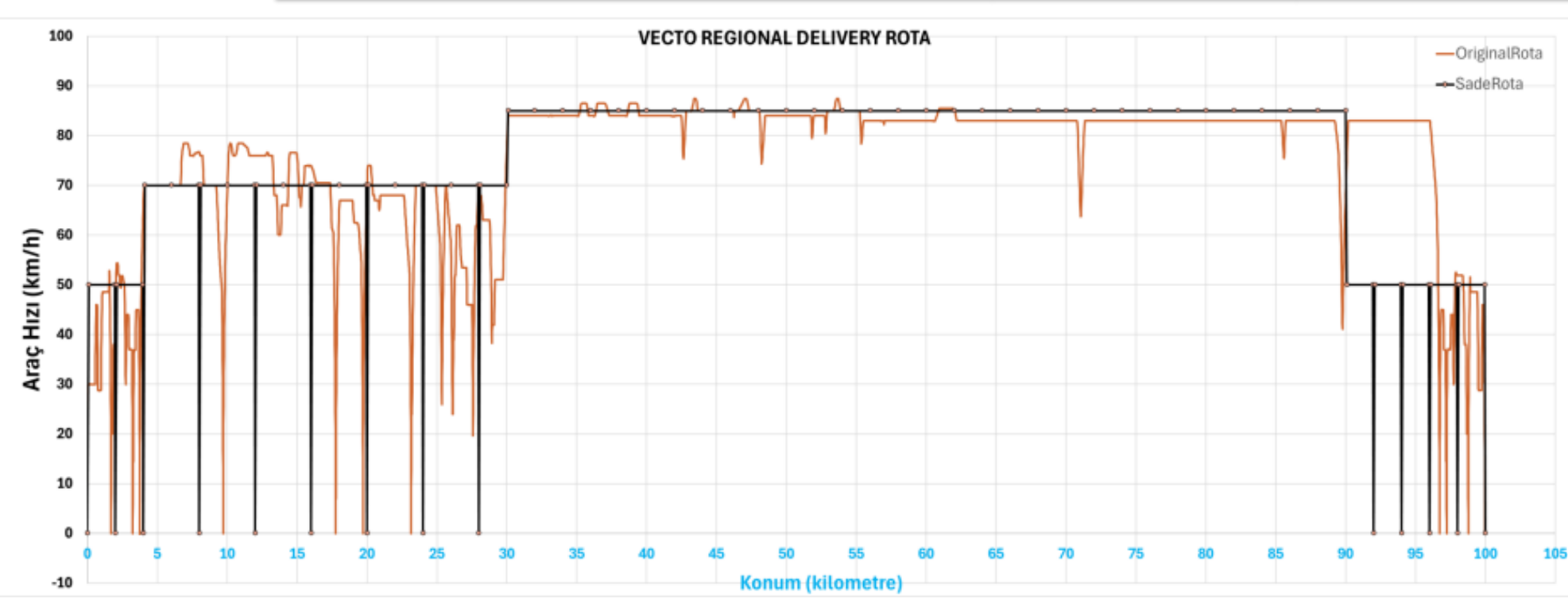


Consistent torque behavior achieved across hardware variants



# Demo Route Profile & Details

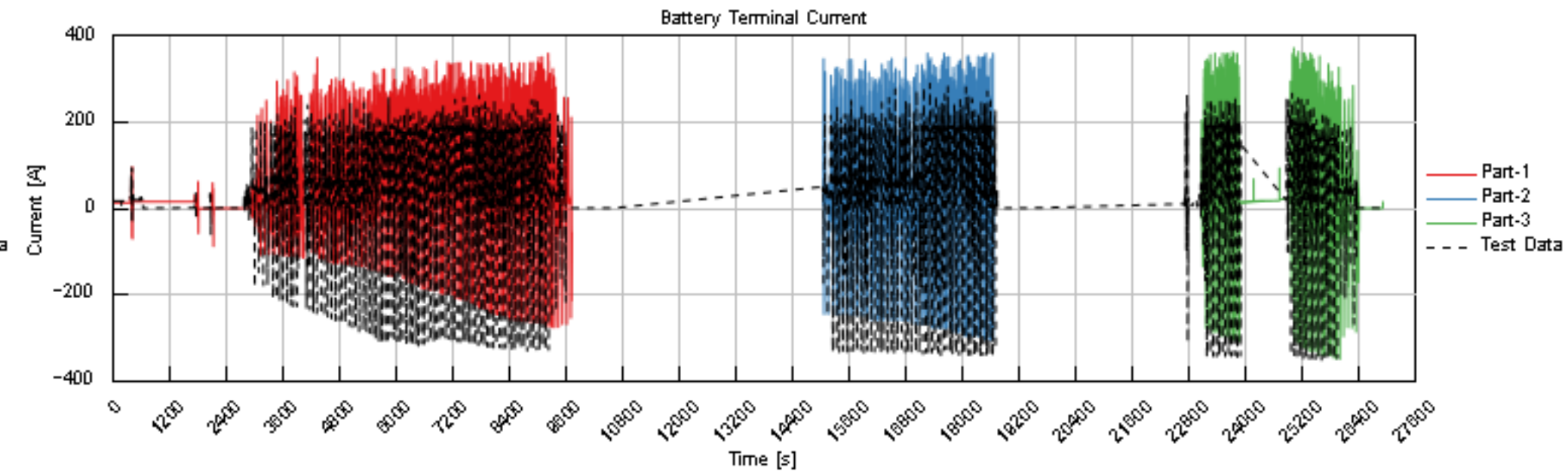
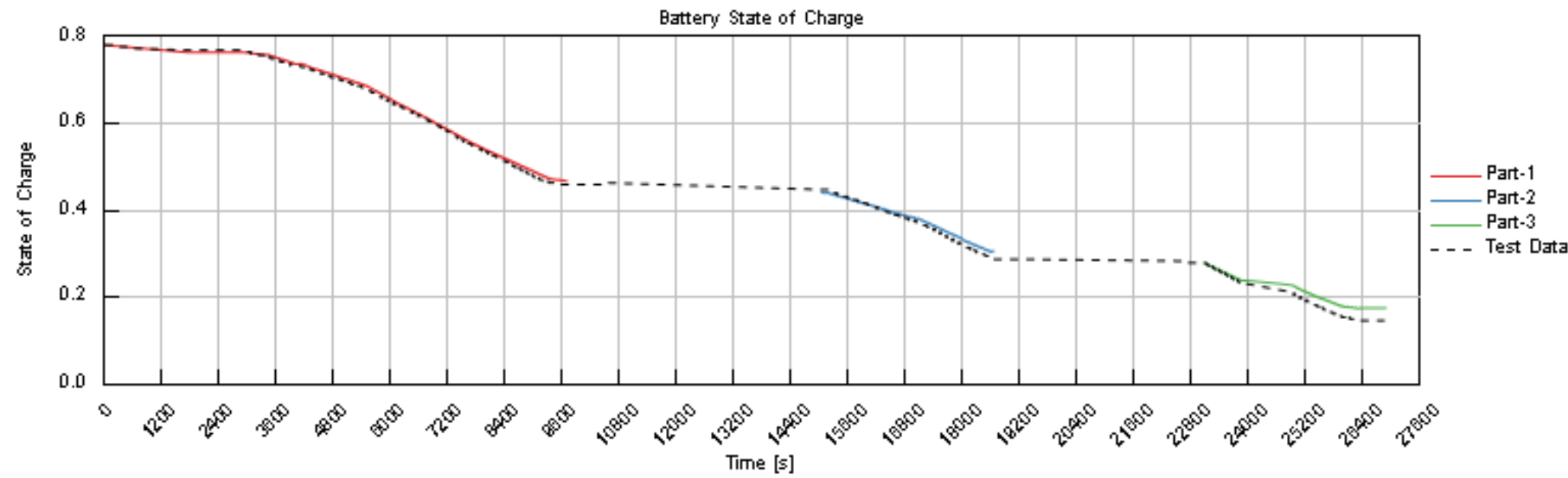
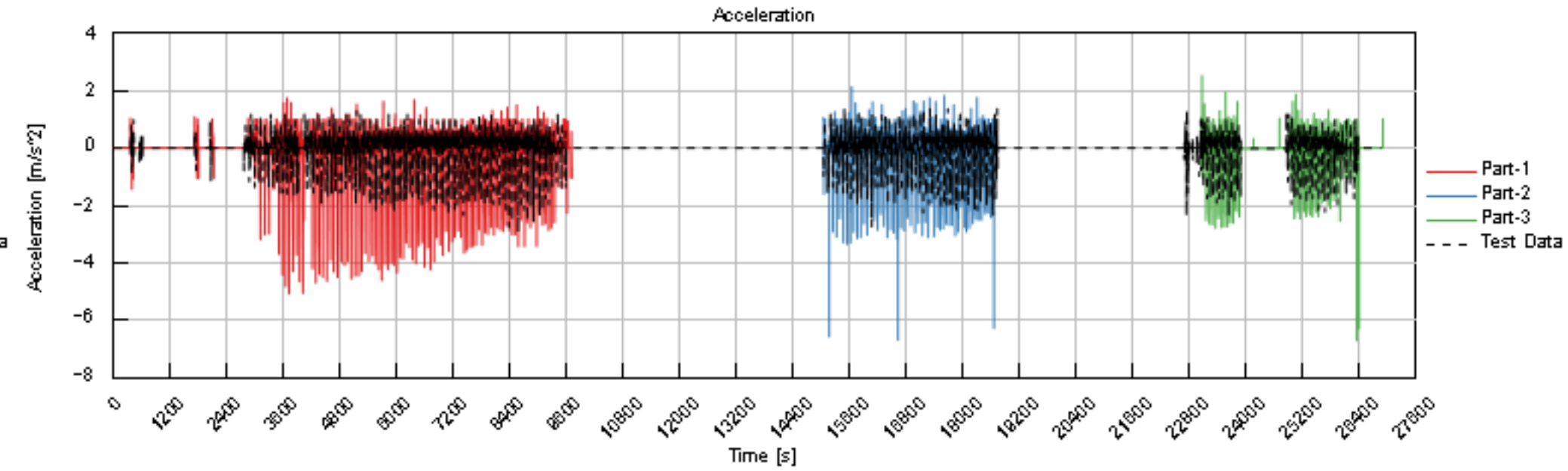
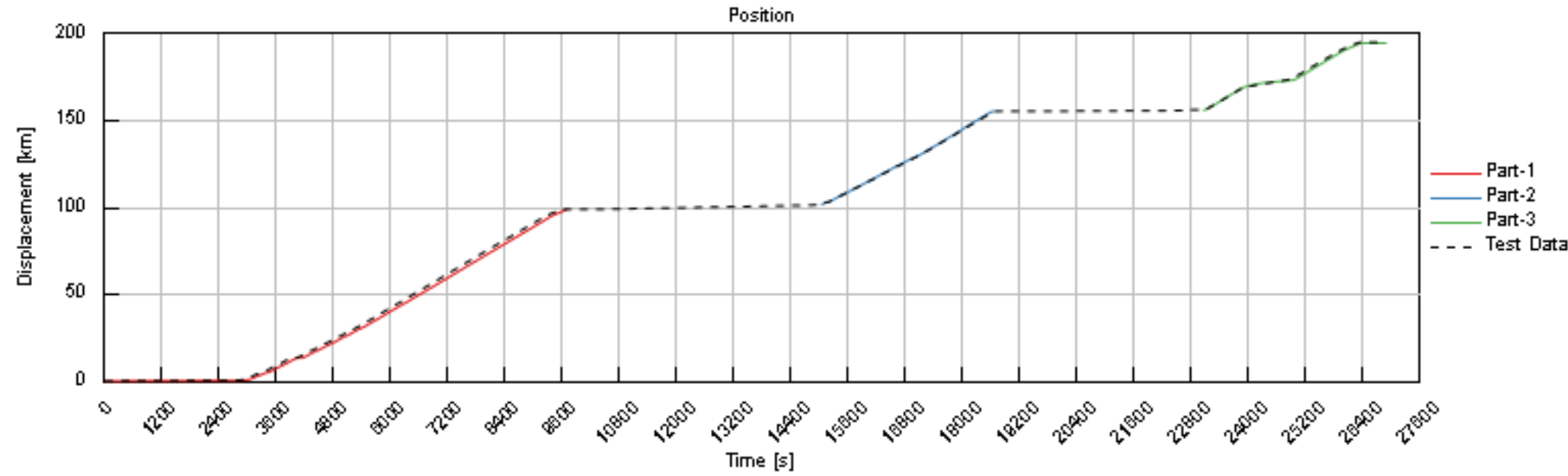
Distance & Lap	Target Speed	Notes
Preparation Phase	-	The vehicle must be fully charged first. Wait at least 30 minutes after charging.
Laps 1 and 2	~ 50 km/h	The vehicle must perform a full stop-and-go at the end of each lap.
Laps 3 to 15	~ 70 km/h	The vehicle must perform a full stop-and-go every 2 laps.
Laps 16 to 45	~ 85 km/h	Continue driving without stop-and-go.
Laps 46 and 47	~ 50 km/h	The vehicle must perform a full stop-and-go at the end of each lap.
Rest Period	-	The 2nd phase will be an exact repeat of the first 47 laps. However, the vehicle must be rested for 30 minutes before the 2nd phase.
Laps 48 and 49	~ 50 km/h	The vehicle must perform a full stop-and-go at the end of each lap.
Laps 50 to 62	~ 70 km/h	The vehicle must perform a full stop-and-go every 2 laps.
Laps 63 to 92	~ 85 km/h	Continue driving without stop-and-go.
Laps 92 and 93	~ 50 km/h	The vehicle must perform a full stop-and-go at the end of each lap.
Battery Depletion	Free Driving	If the battery is still not depleted after 93 laps, continue free driving until the battery is completely depleted.



The 200 km daily driving cycle combines rolling VDT regional delivery operation with low-speed LLT urban driving, fully aligned with the VECTO Regional Delivery cycle and optimized for energy consumption and thermal stability assessment.



# Internal Test Data & Model Comparison





# EFFECTIVE ENERGY MANAGEMENT

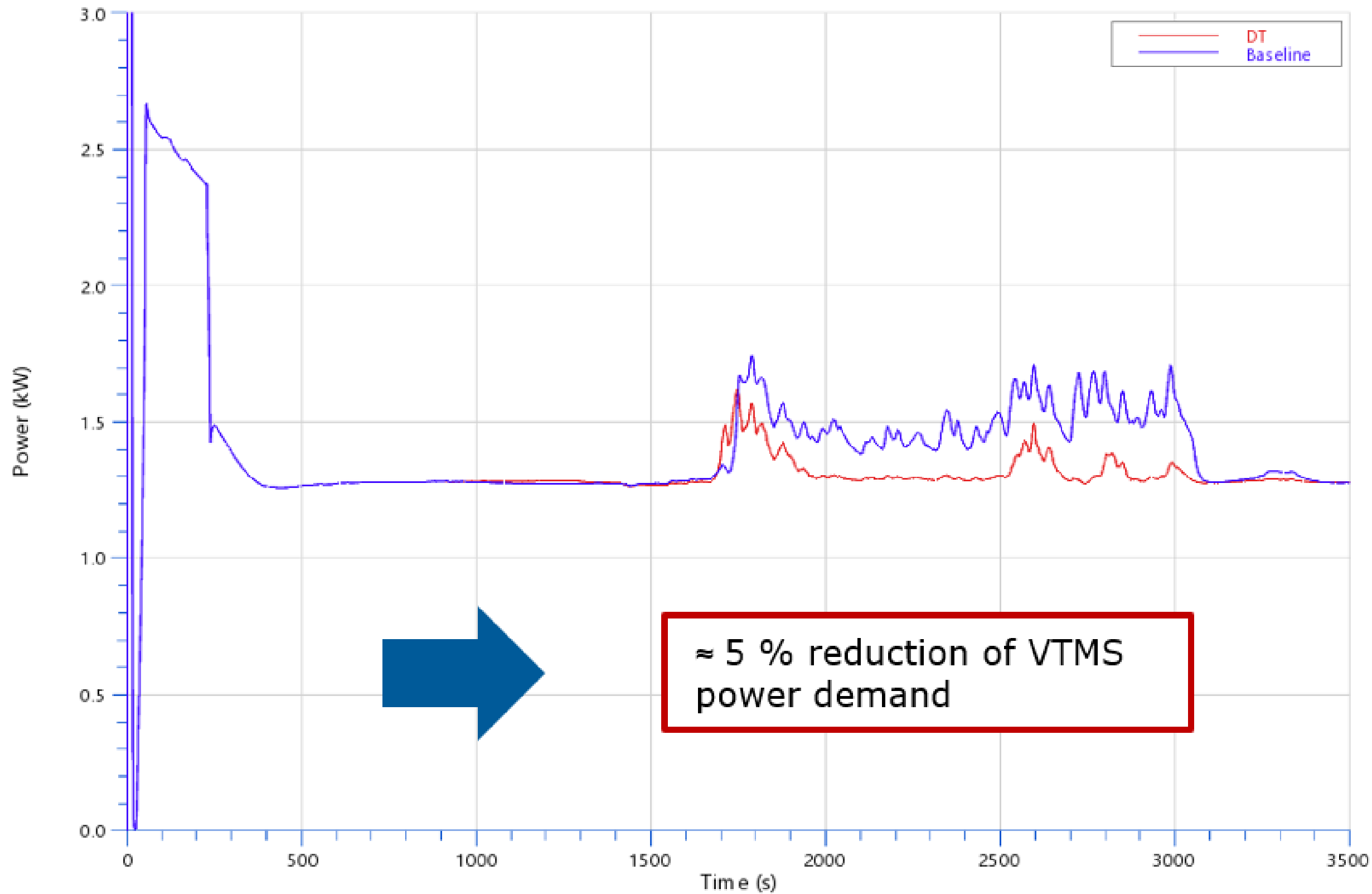


**FORD** OTOSAN

Next   
EIRUCK



# Digital Twin: Benefit in Simulation



By using a higher setpoint, which is verified predictively, savings of up to **5% TMS energy** consumption and **0.3% vehicle energy** saving can be achieved.



# Thermal System: Benefit in Simulation

15% Thermal Efficiency Improvement Target

15%

✓ Done – Will be demonstrated on the vehicle

★ Assessment Completed.

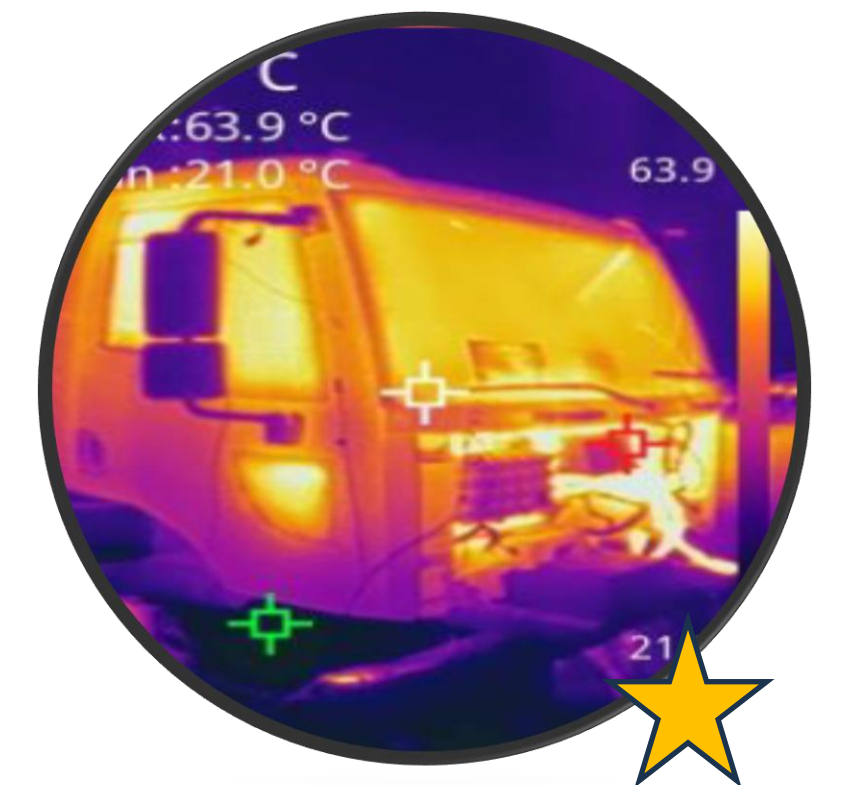
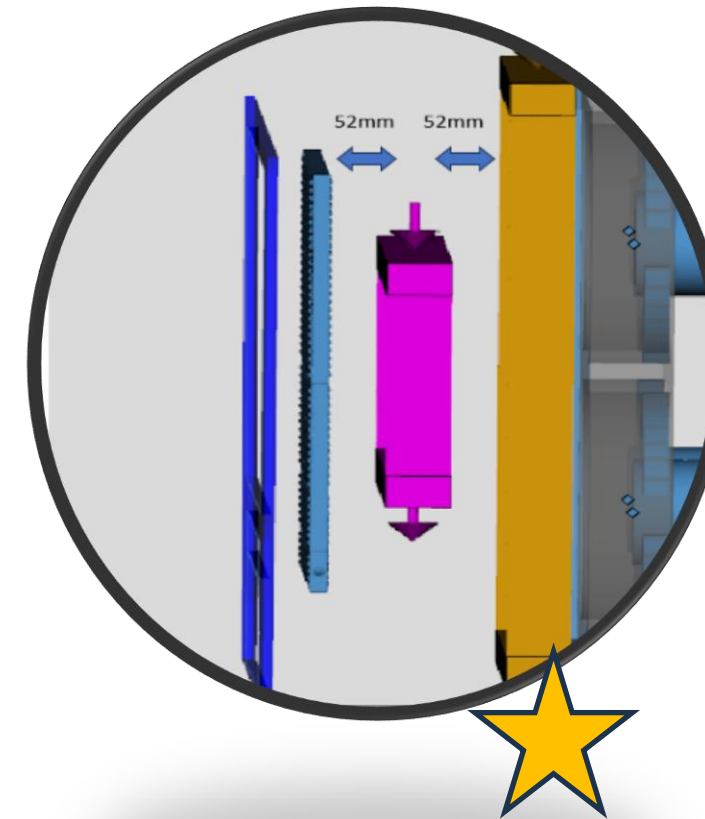
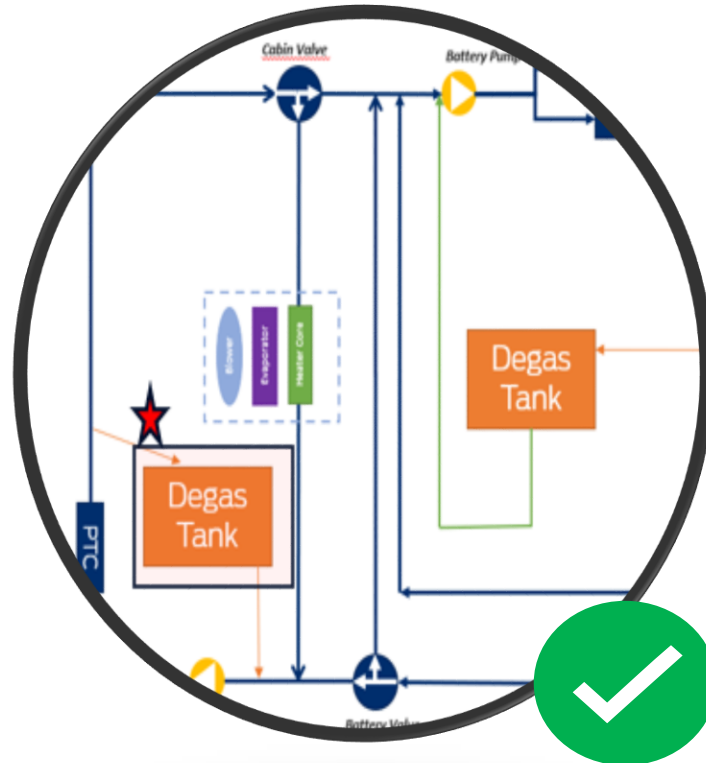
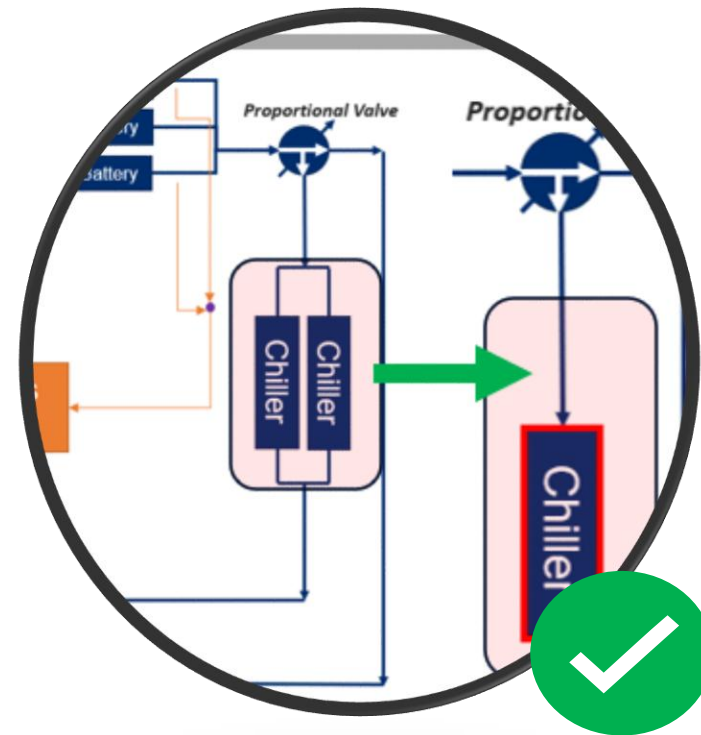
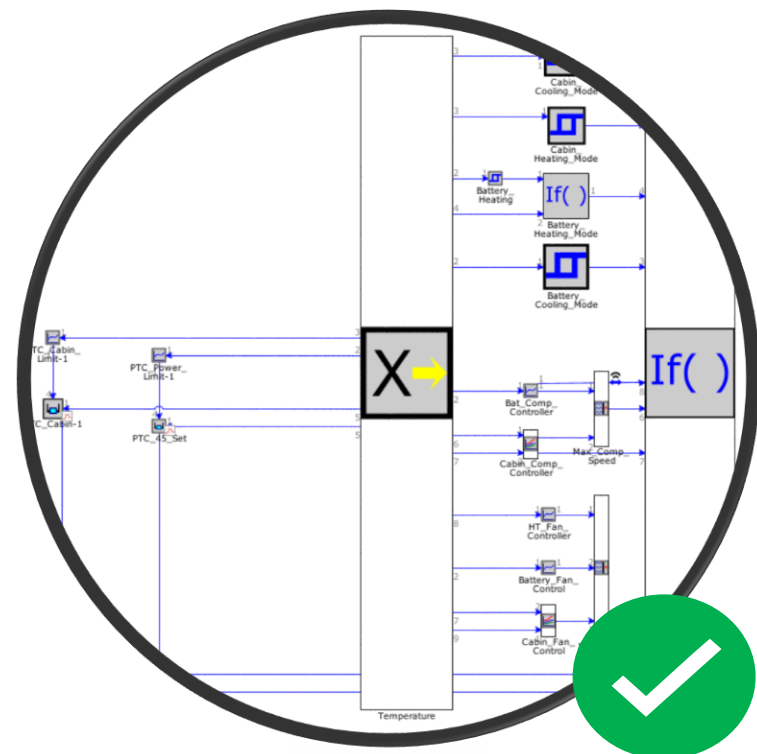
## Degas Solutions

## Battery Cooling - Chiller

## Active cooling for battery

AIT (Austrian Institute of Technology) / Cabin Improvements

## Calibration improvements



## Improvements;

1. Up to 20% improvement for winter case from degas study
2. Up to 8% improvement for summer case from chiller study
3. Up to 40% improvement for spring case from active cooling(in progress)

Up to 1,1% improvement overall vehicle energy efficiency for winter case from degas study

Next e Truck



Rigid e-Truck 4x2



# Powertrain: Benefit in Simulation

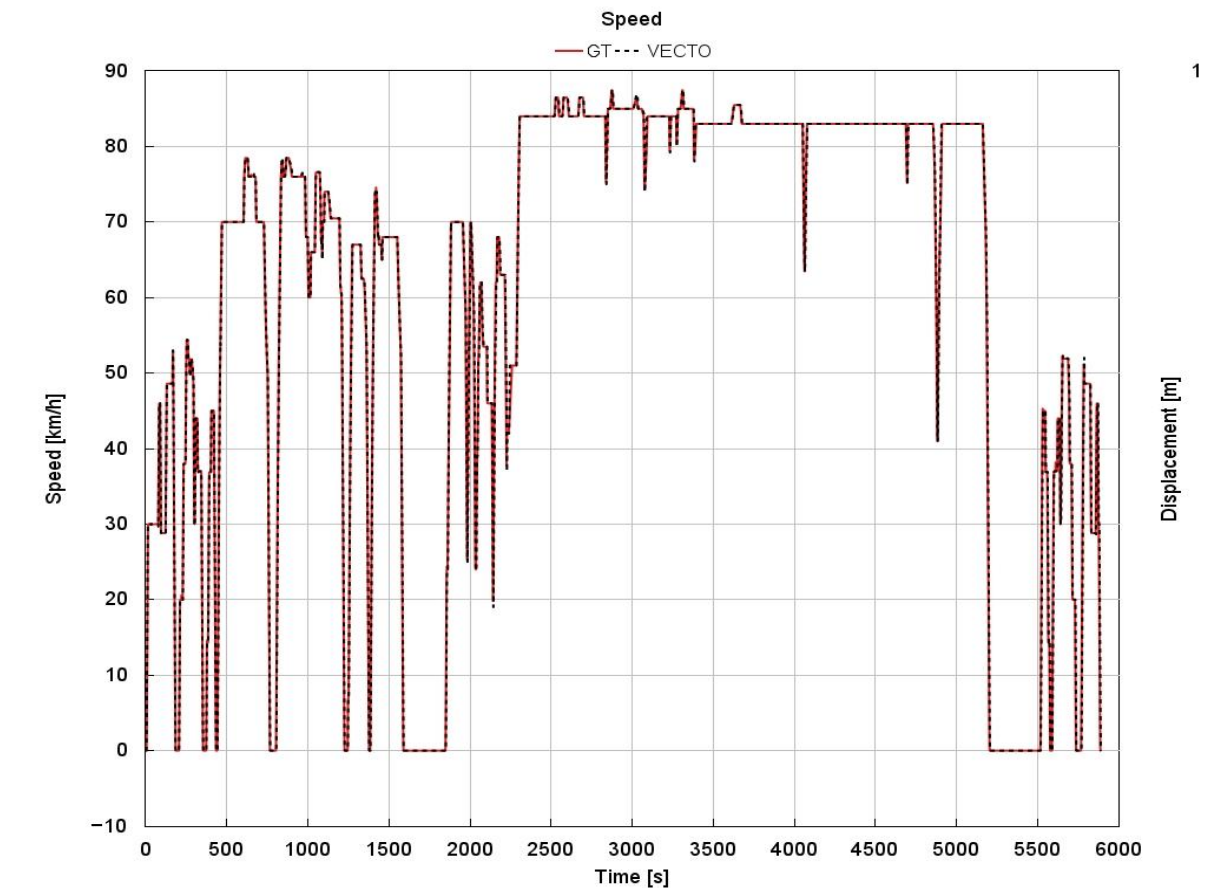


**Baseline; F-Line BEV (4x2, 19T)**



**NextETRUCK Vehicle (4x2, 16T)**

Parameter	Baseline Truck (Rigid 4x2 – 19t)	NextETRUCK (4x2 – 16t)
<b>Battery Configuration</b>	3-pack, 294 kWh	3-pack, 294 kWh
<b>Continuous Power Output</b>	234 kW (voltage-limited) – Central Drive	210 kW (fully usable) – e-axle
<b>Peak Torque</b>	24,700 Nm	26,000 Nm
<b>Payload</b>	~9.1 t	9.1t
<b>Usable Energy of Battery</b>	~235.2 kWh	~235.2 kWh
<b>Average Energy Consumption</b>	0.974 kWh / km	0.895 kWh/km (%8,2 efficient)
<b>Estimated Loaded Max Range</b>	~242 km	~ up to 316 km
<b>Energy Efficiency (kWh/ton-km)</b>	0.107 (Calculated with 9.1t sim. payload)	0.097 (Calculated with 9.1t sim. payload)



**VECTO Regional Delivery route is used in the simulations.**

$$\text{Energy Efficiency (kWh/ton-km)} = \frac{\text{Energy Used}}{\text{Payload} \times \text{Distance}}$$

**9.3 % Energy Efficiency (kWh/ton-km) improvement with simulations**



# Energy Efficiency Executive Summary

0.3 % Digital Twin: Thermal Energy Efficiency Improvement

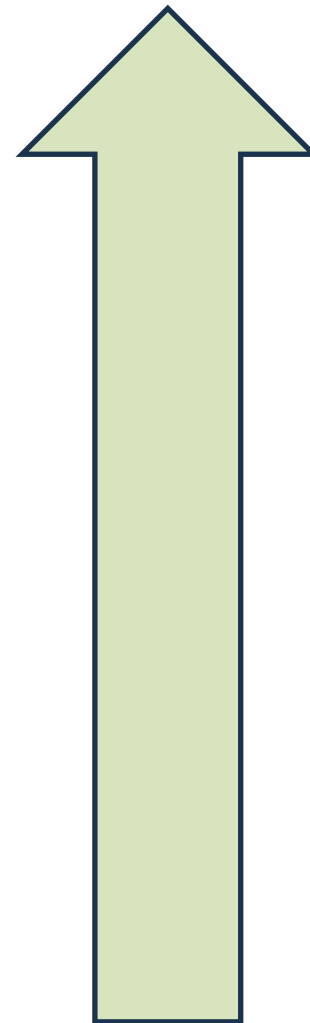
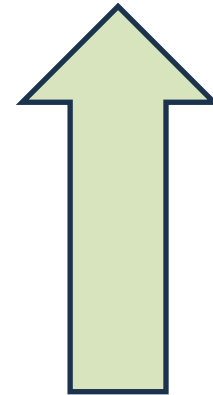
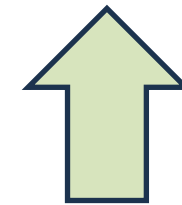
1.1 % Thermal Energy Efficiency Improvement

9.3 % Powertrain Energy Efficiency Improvement

Baseline -NextETRUCK



Base Line – 4x2, 19T F-Line BEV



10.7 % Vehicle Energy Efficiency Improvement is reported.



Next e-TRUCK Vehicle  
4x2, 16t New BEV Platform



# Thank you for your attention!



@nextetruck



NextETRUCK



nextetruck.eu



Co-funded by the European Union



Co-funded by UK Government

This project has received funding from the European Union's Horizon Europe programme under grant agreement No 101056740

