

**Introduction of Digital
Twins and Tools for
NextETRUCK**

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Digital Twinning & Virtual Integration

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EFFICIENT POWER ELECTRONICS,
POWERTRAIN & ENERGY SOLUTIONS
RESEARCH GROUP



Different types of digital twins

Digital Model

Virtual representation of a physical system
No interaction between system and model

Digital Generator

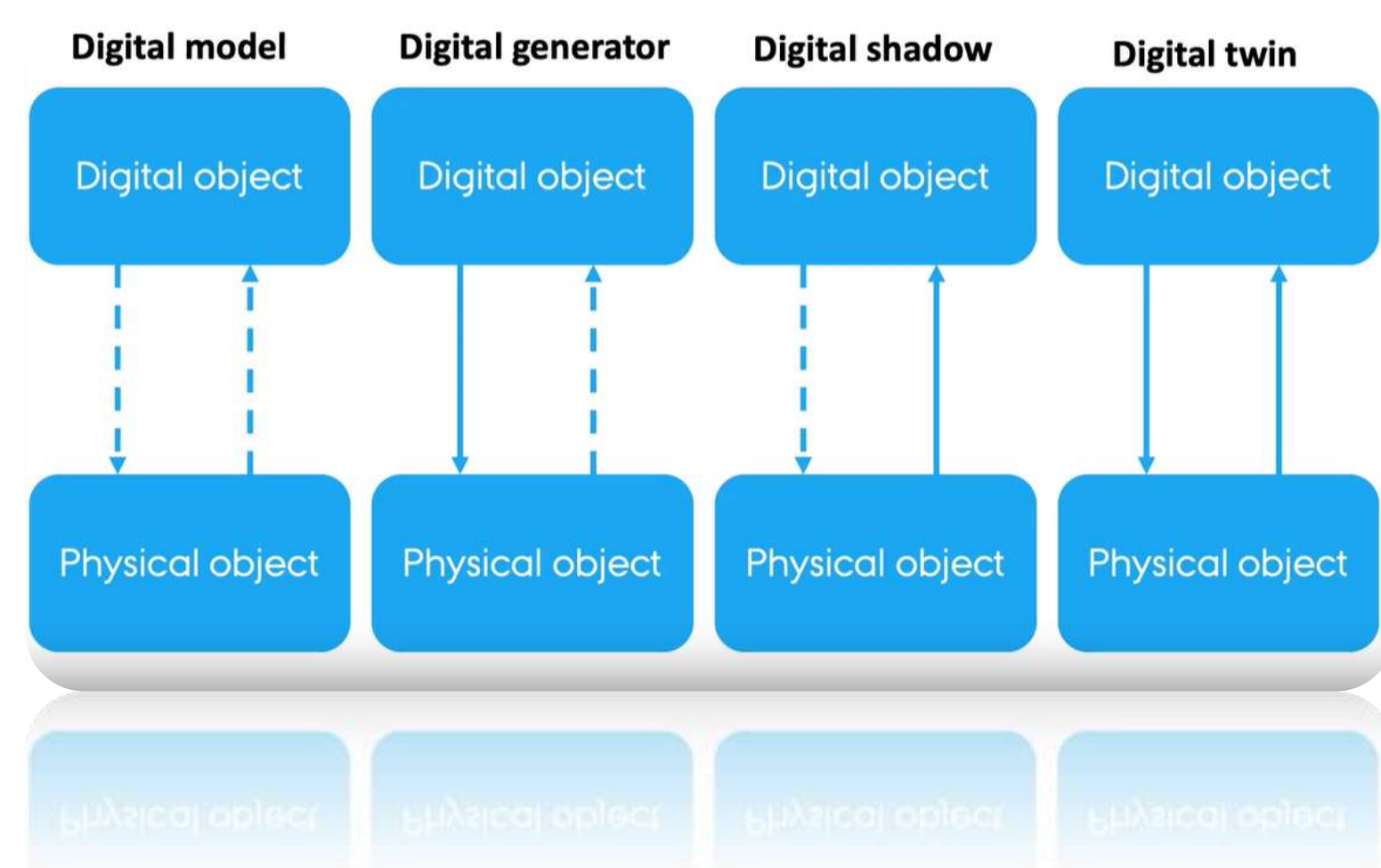
Physical system follows the model

Digital Shadow

Model follows physical system

Digital Twin

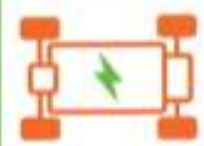
Virtual representation of a physical object or process
Bidirectional exchange of data between physical and virtual system
Used for process optimisation, observation, prediction,...





Why Digital Twin(s)?

5 key innovations



Advanced electric powertrains

Modular design
Regenerative braking
Energy loss reduction



Digital twin and fleet management tools

Cost savings
Environmental benefits



Tools to optimize design and reduce costs

Improved vehicle cabin
HVAC system



New business models to increase widespread market

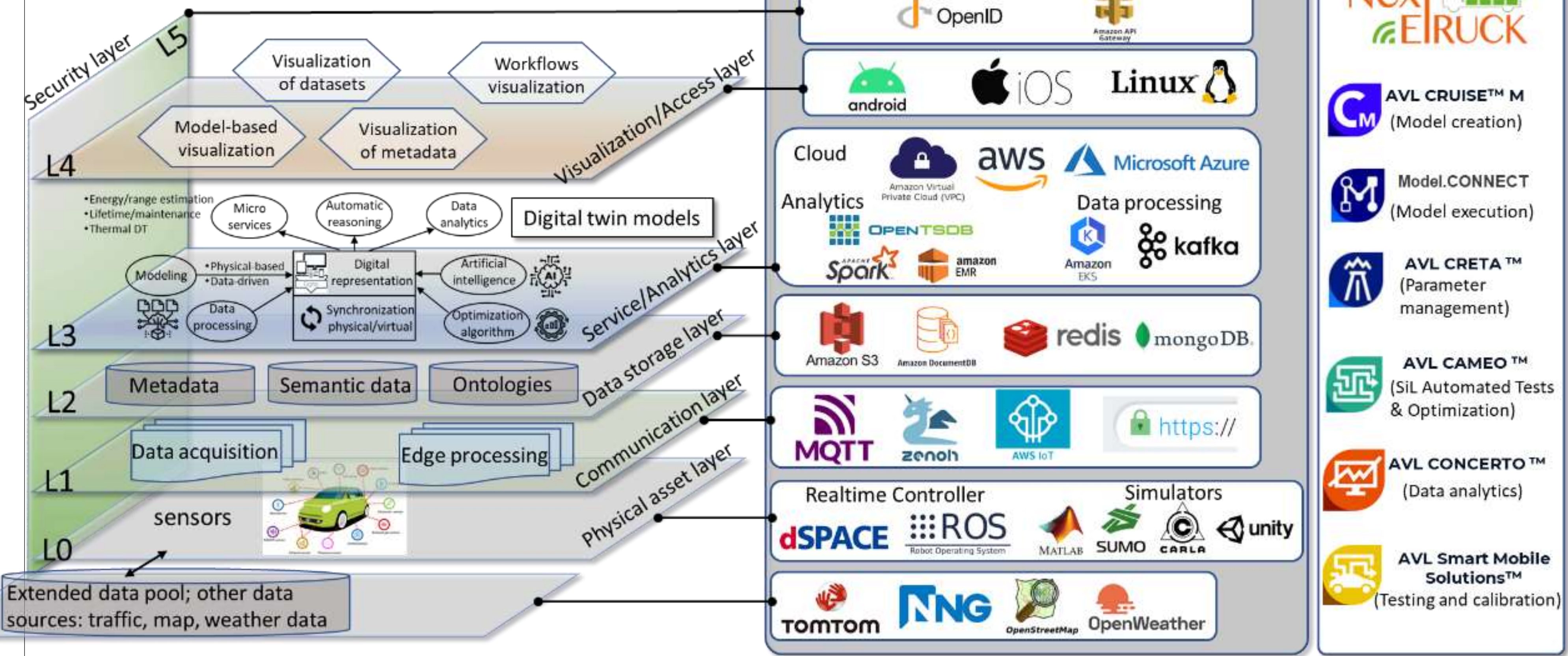
Circular economy
Repurposed batteries



Flexible ultra-fast charging concepts

Minimise charging costs
Avoid peak demand

Layers for Digital Twin



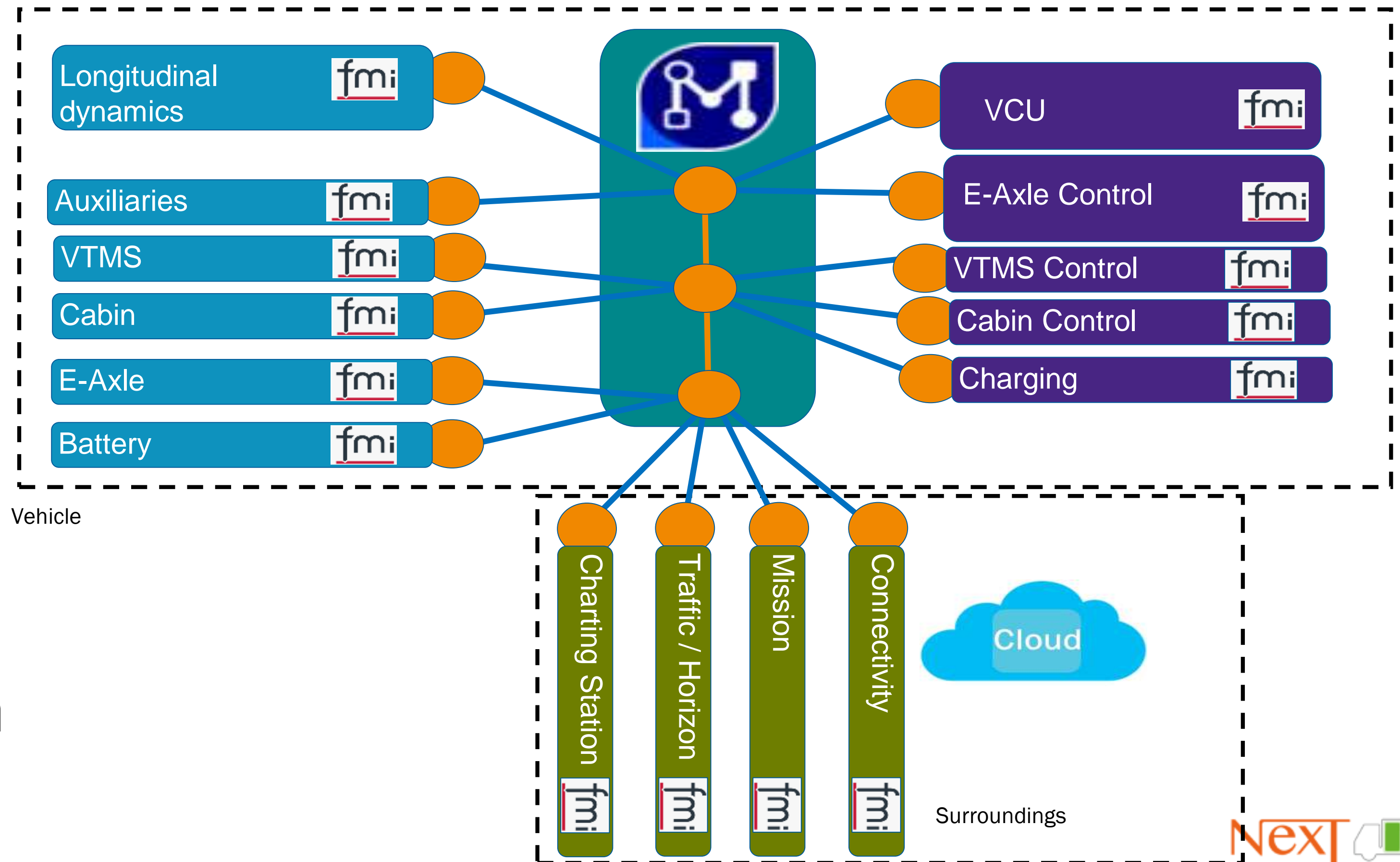
Multi-layer digital twin architecture

Existing Commercial Software Tools
(highly heterogeneous)

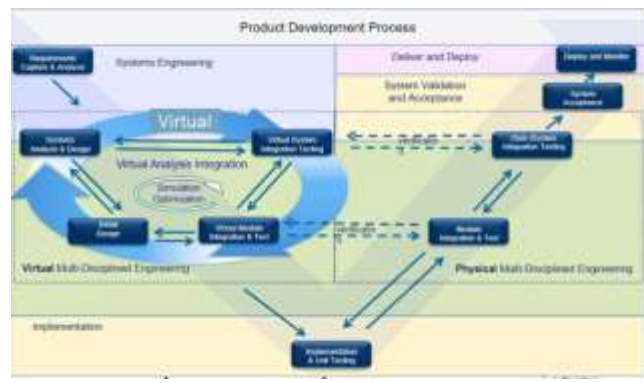
NextETRUCK
Digital Twin Platform
TNO innovation for life



DGT-concept



NextETruck
Digital Twin



System definition

- System modeling/ SysML
- Use cases
- Architecture/ interface



Model calibration

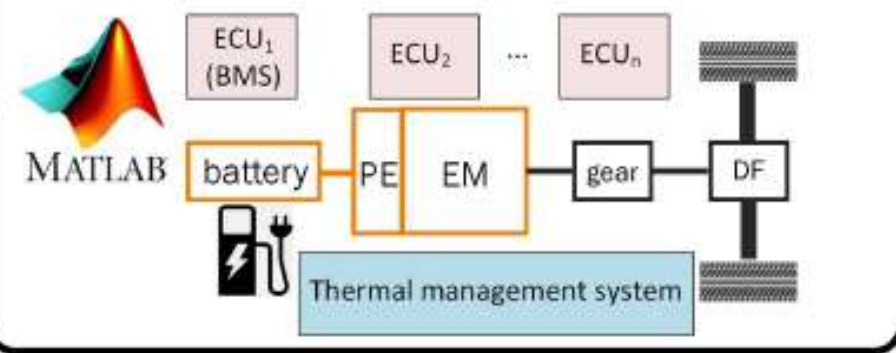
- Sub-system model identification and verification
- Autonomous calibration

Simulation

Simulation parameters

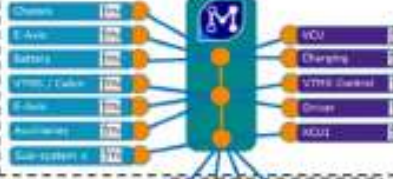
- Vehicle parameters
- Ambient parameters
- Depot locations
- Charging facility locations
- Grid, schedules

Matlab/Simulink Simulation Model (Powertrain, thermal, E/E, ECU)



Co-simulation

fmi Functional Mock-up Interface



- Real-time capability models
- Scalable models
- Model.CONNECT™ platform

Cloud/ edge computing/ IoT setup

Data fusion

Optimization loop

- Objective functions
- Constraints
- Searching algorithm

No

Terminating condition?

Yes

Optimal sizing solutions

TCO calculation

Cost parameters

- Unit cost data
- Component service life
- Discount rate
- Interest rate
- Cost escalation/ degression per component

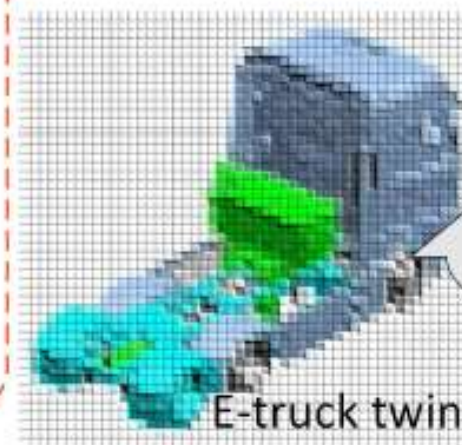
TCO model

- CAPEX model (vehicles, batteries, infrastructure)
- OPEX model (driver, energy, maintenance)

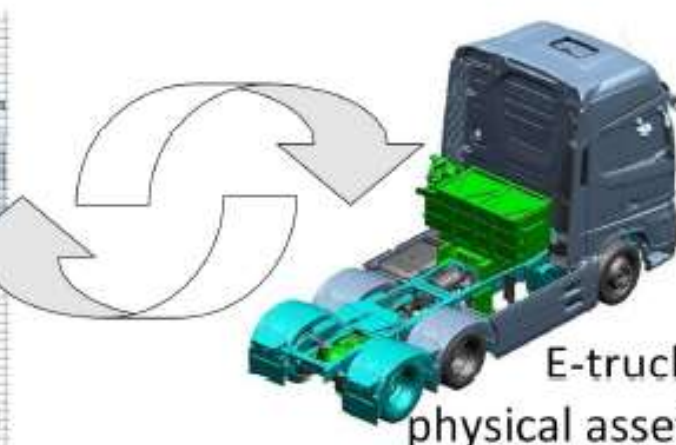


Simulation results

- Energy consumption
- Vehicle states (SoC, power, ...)
- Charging states (occupation, power)
- Depot states



E-truck twin



E-truck physical asset

Pre-sizing optimization

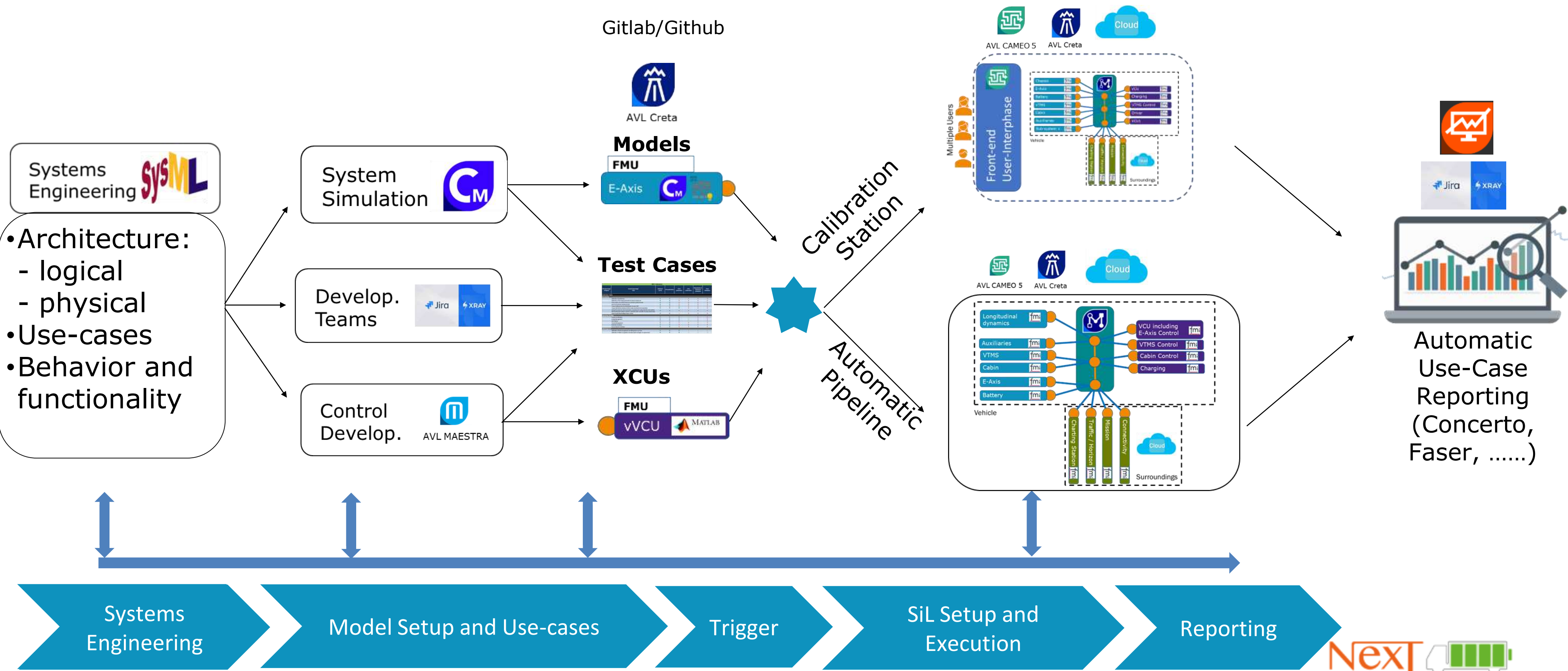
MiL/HiL/Model Calibration

Data/IoT

Sensors



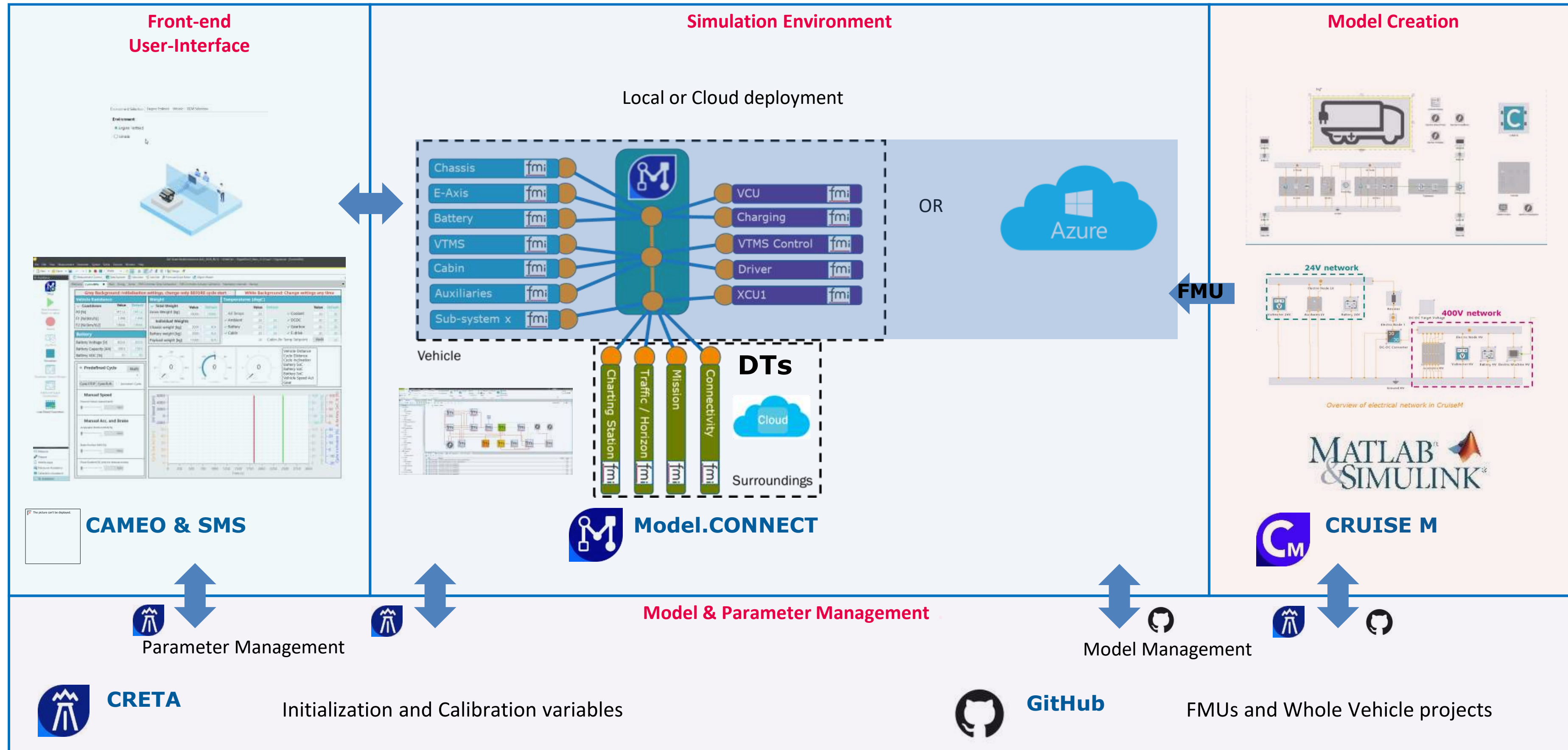
Example of SiL setup (as development and test tool)



NextETRUCK Baseline Vehicle environment

Multiple Users

DB Managers





Big Picture

FAST Digital Twin:

- DT Energy Consump. Charact. (AVL)
- DT Multi-Level Ctrl Sys. Opt. (TEC)
- DT Battery Age (TNO)
- DT Charge Time Est. (TNO)

- Charge Manag. Platform (PANION)
- Logistics Planner & Mission Assignm. (CERTH)
- Modular IoT & Fleet Manag. (DATIK)
- Traffic Flow Info, Routing & Content (NNG)

Real time Digital Twin:

- DT Cooling Sys. Model (AVL-D)
- DT Veh Cabin & HVAC (AIT)
- DT Eco-Driv. Feedback w/ HVAC (VUB)
- Virtual Vehicle (VUB)**
- BMS & HVB LF Model (CID)

Actual conditions

Real, physical Vehicle

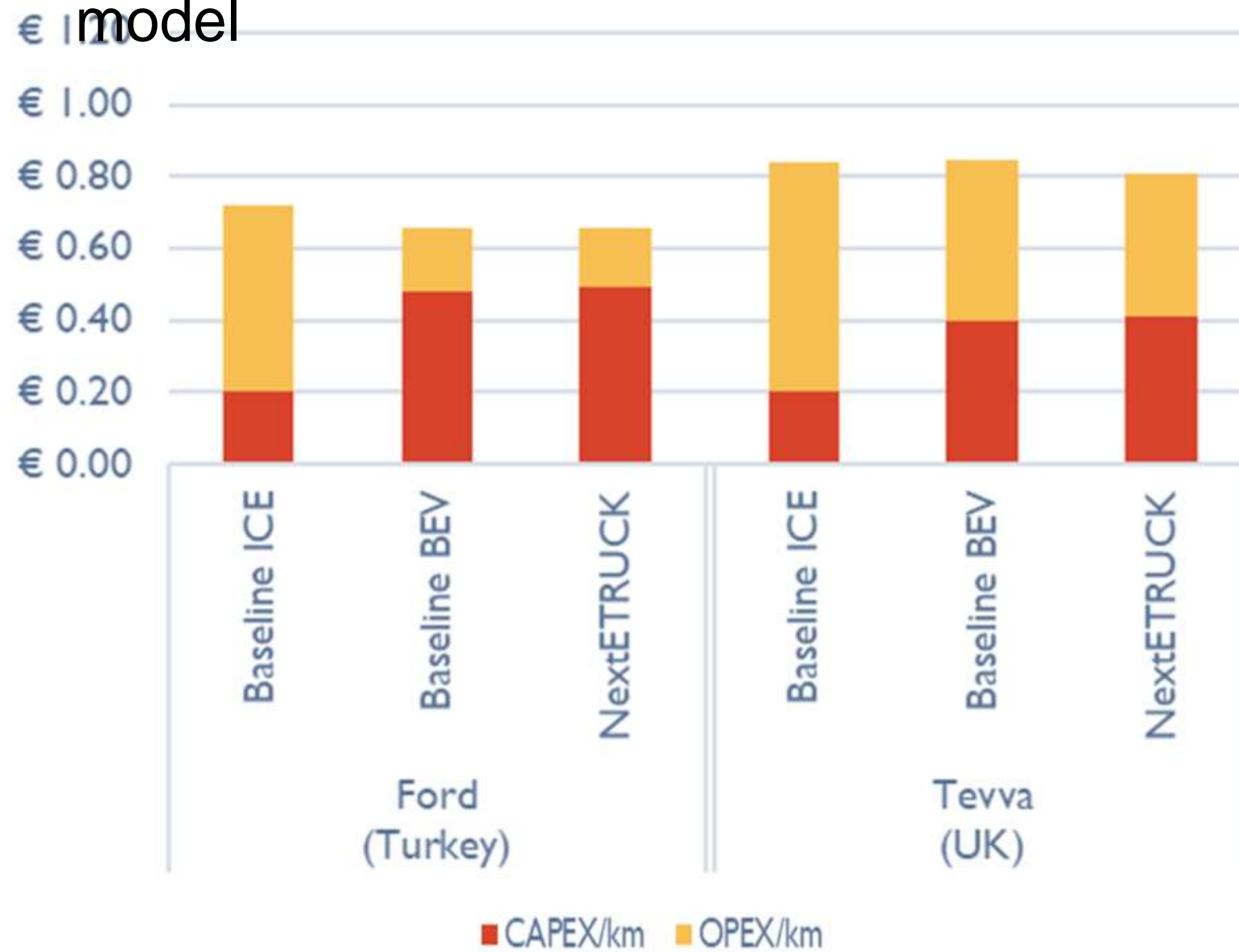
Optimized (logistic) decisions for the near future

- CHARGE INFRASTRUCTURE (IEMA)
- Physical Systems

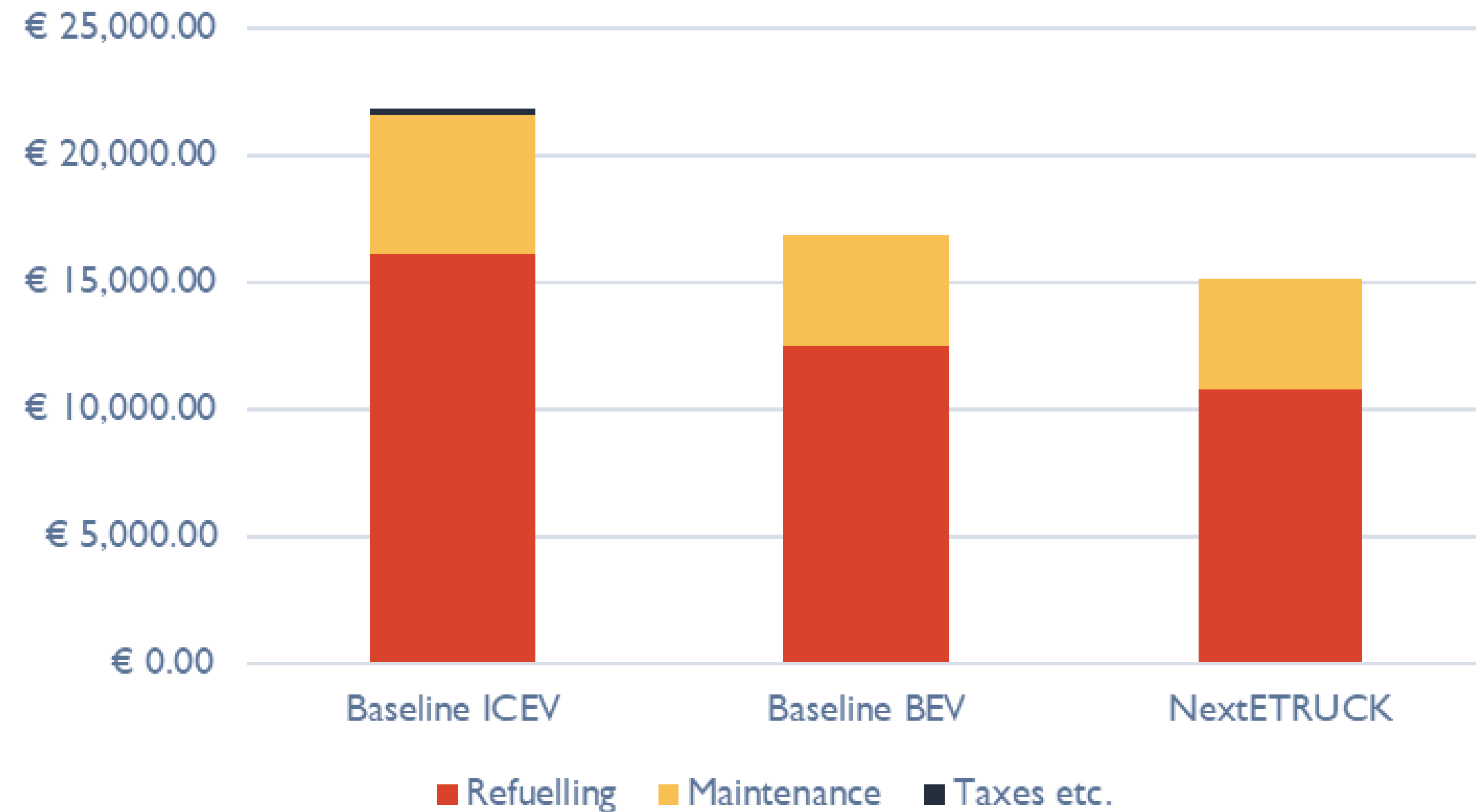


Results for Design Optimization of BEV Trucks

TCO per km for the generic 16-ton truck model

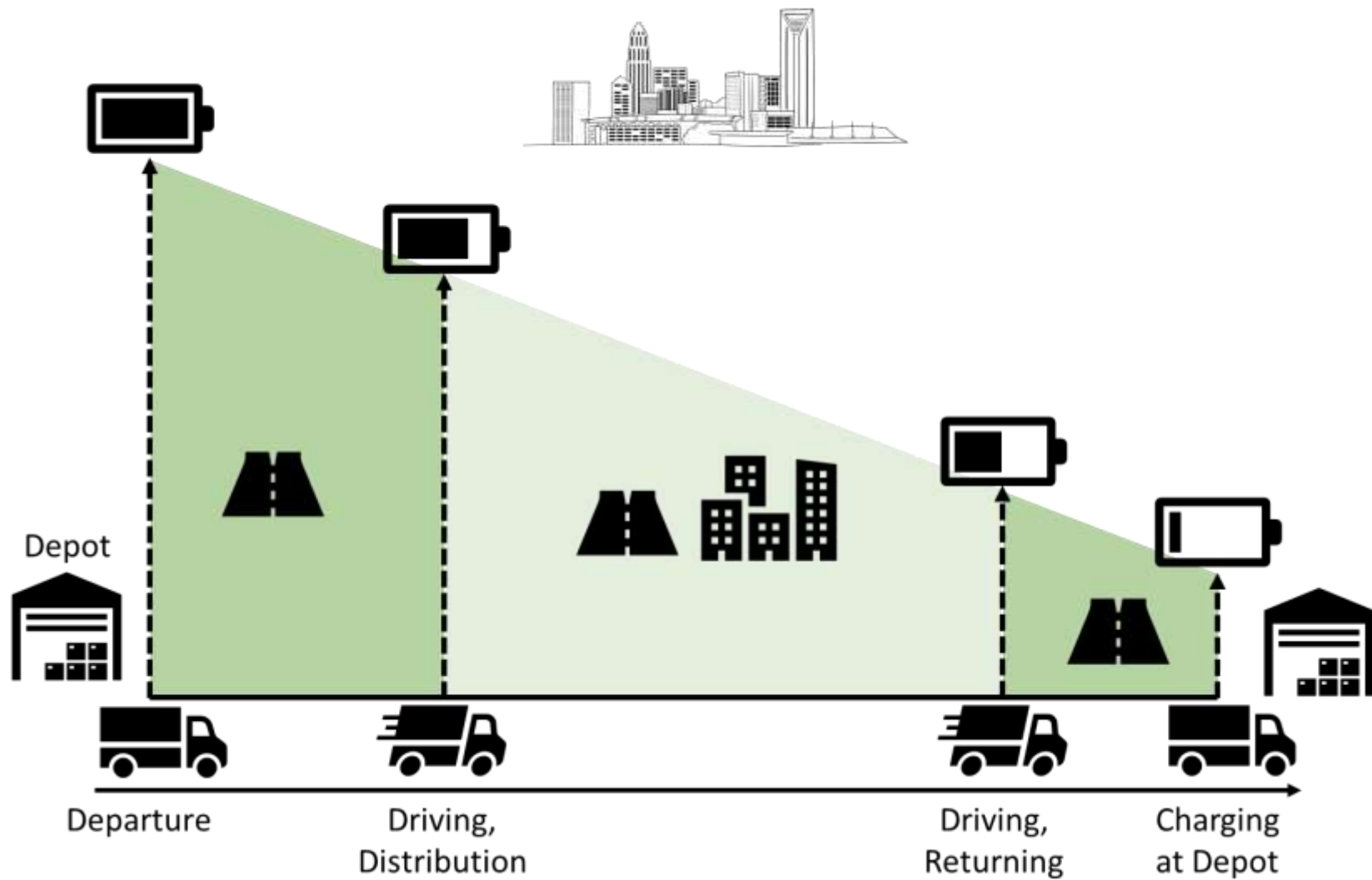


OPEX breakdown

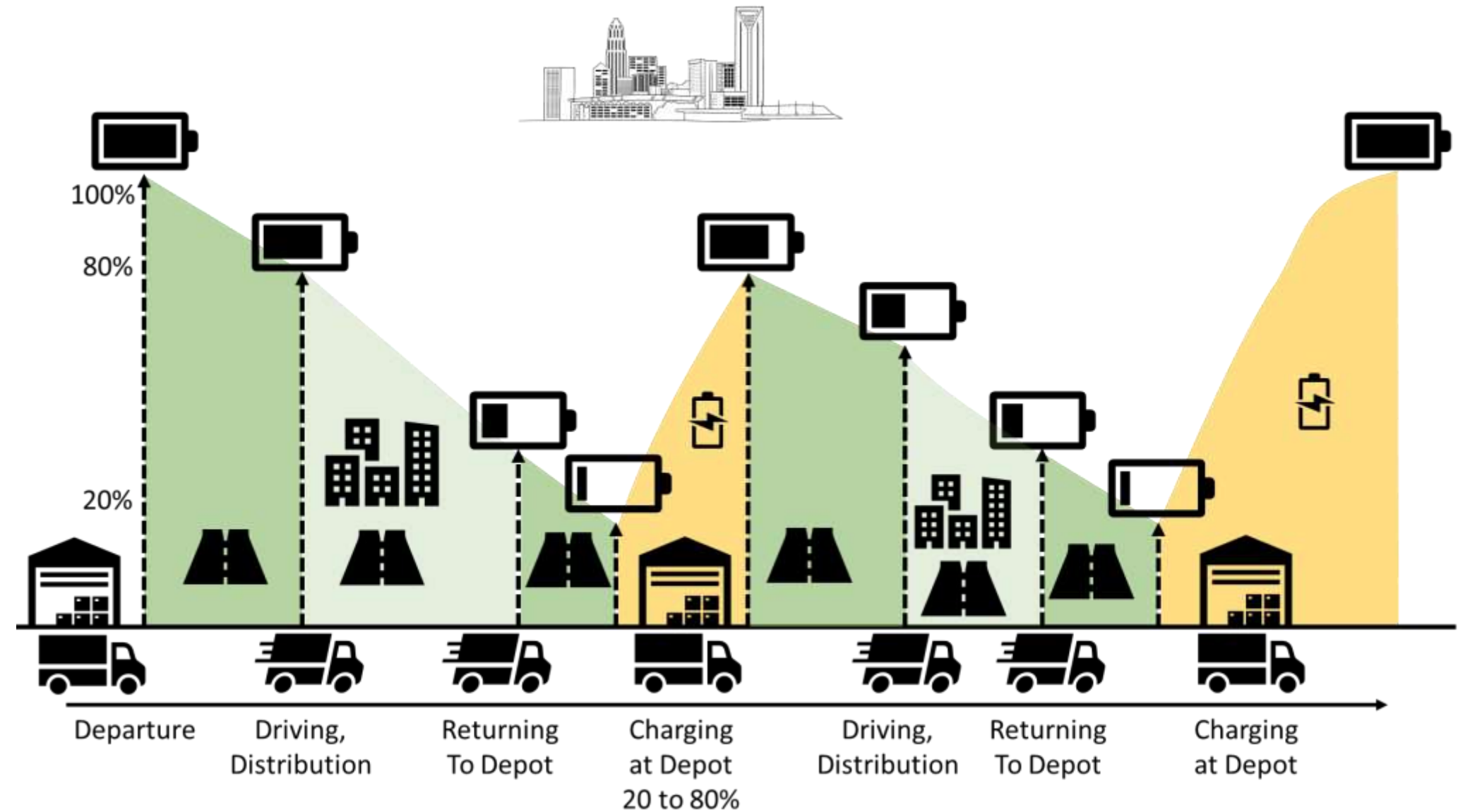




Charging strategy and Planning



a) Charging strategy when the truck drives from and to a depot with deliveries in between, without requiring a charging stop in the day.



b) Charging strategy when the truck requires to have charging stops in the day to ensure the operations can take place during the day.



Next ETRUCK



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