Task 3.4: Modular and Interoperable IoT system design AVL-AT (L), TEVVA, IRIZAR, TEC, DATIK; M10-M18

Overview of innovative measures

Leo Xenakis & Hans-Michael Koegeler AVL-AT (L) Brussels, Feb 2024

Co-funded by the European Union

ERUCK



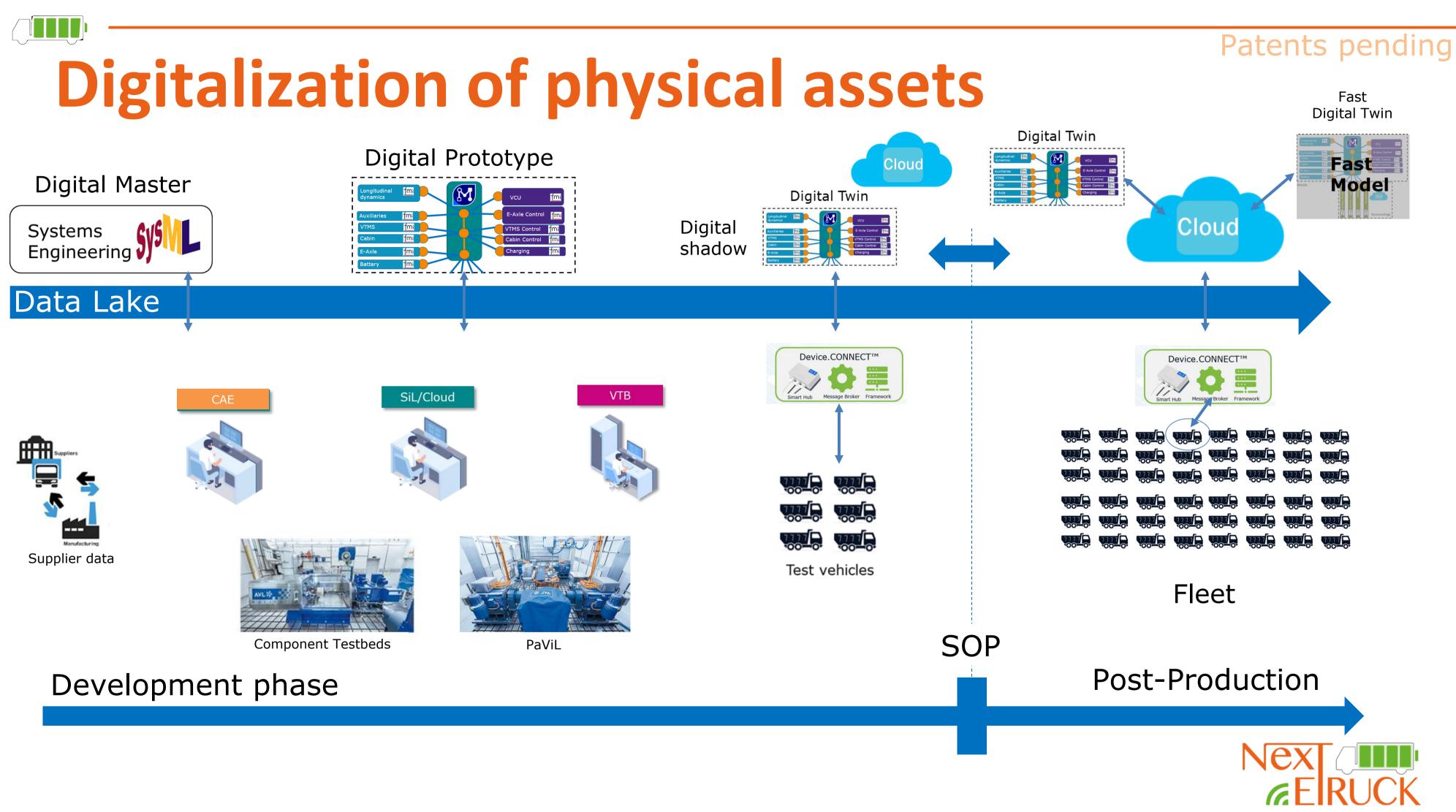
Task Description and Objectives

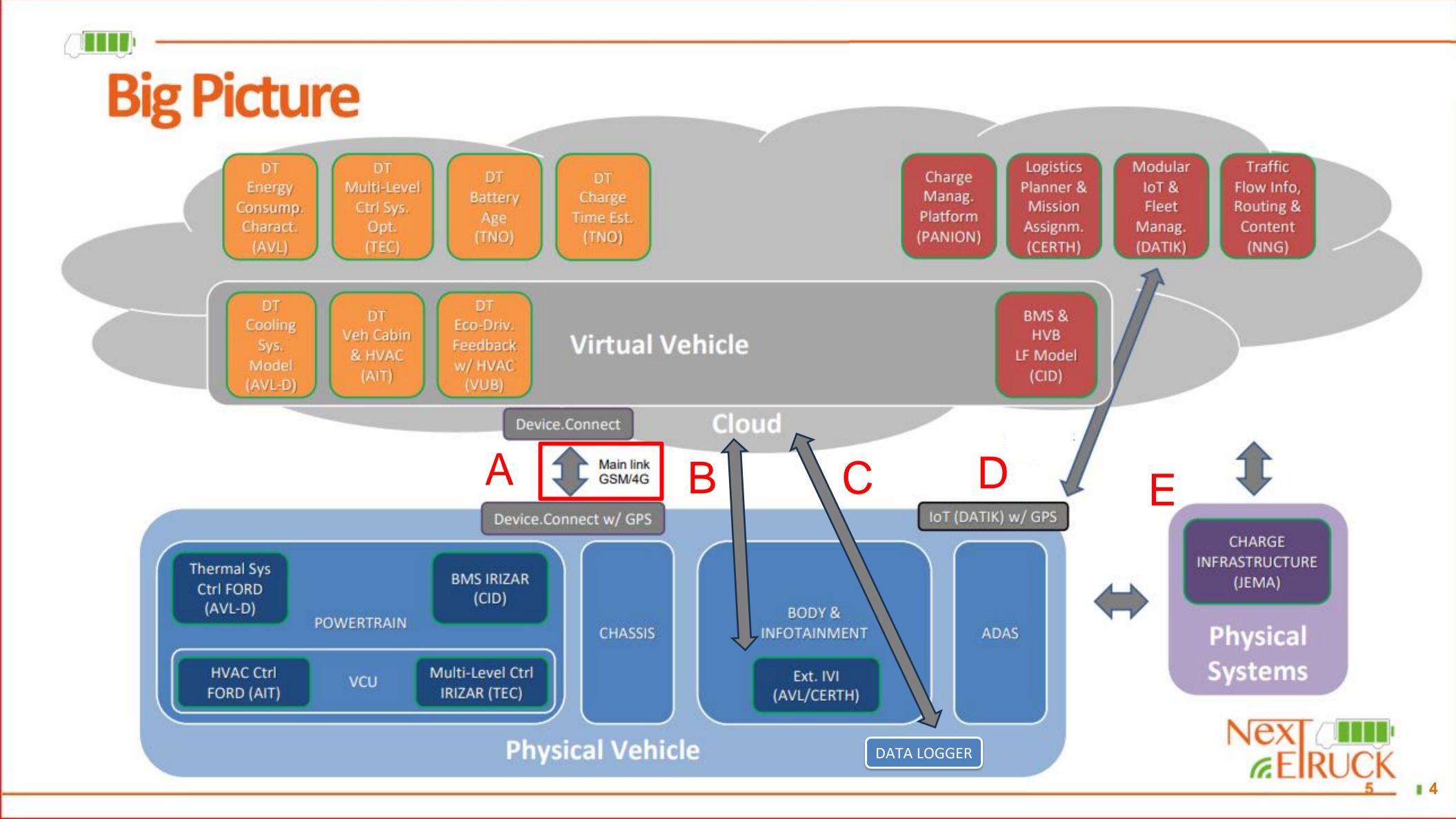
Task 3.4 Design of interoperable IoT concept and Interfaces for connected electric truck fleet (AVL-AT(L), TEVVA, IRIZAR, TEC, DATIK; M10-M18)

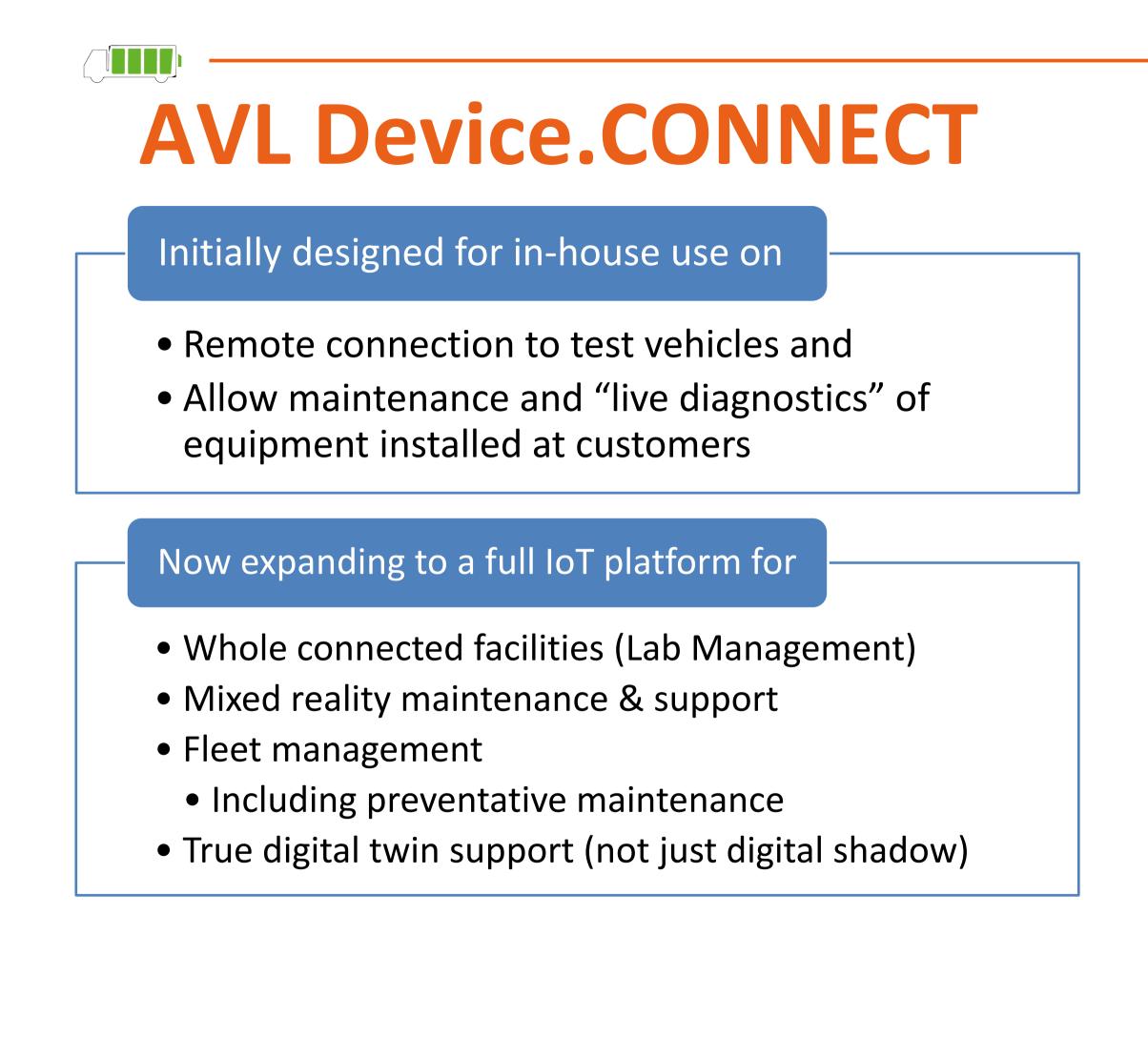
Objectives

- Connects almost anywhere in the world
- High security communications (safety, IP & data protection)
- Flexible, fast bi-directional communications
- Ease of implementation / integration
- Cost effective









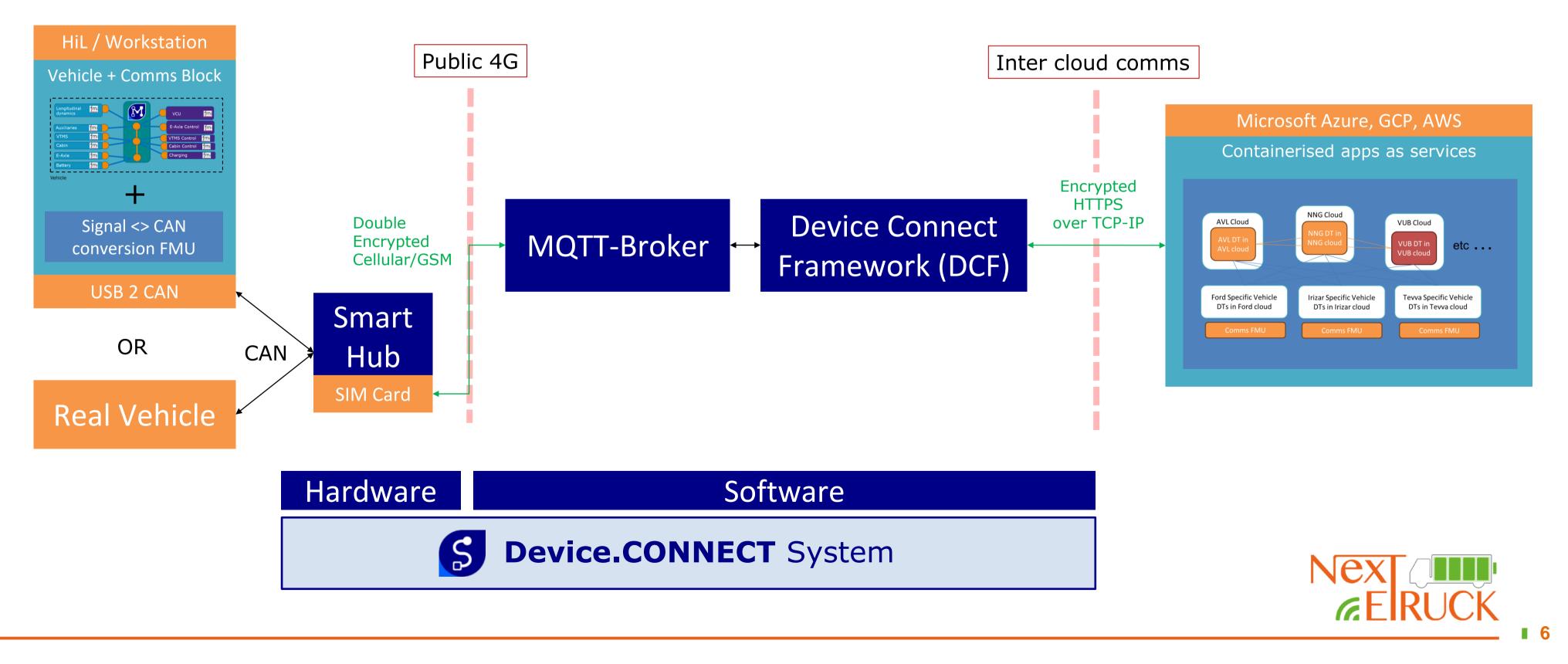




Secure Data Transfer with the Cloud

Real or Simulated Vehicle

AVL Cloud



Cloud Environments

Innovation Areas 1

Connects almost anywhere in the world

- Vehicles, infrastructure, locations and suppliers are increasingly globally distributed \bullet 4G ubiquitous, fast enough for most applications \bullet

High security communications (safety, IP & data protection)

- Secure boot, full disk encryption, ultra high (EAL6+) key store, hardened
- Patented non-routable connectivity approach
- Dual encryption over GSM network \bullet

Ease of implementation / integration

Plug and play \bullet

Cost effective

- Only required interfaces
- Modular approach (support for more on request)
- Flexible production line in place

Generic configurations

	RS 232	USB Device	USB Host	CAN
Ethernet	GY3291	GY3292	GY3522	GY3523
WLAN	GY3292	GY3294	-	GY3524
LTE	GY3524	GY3509	-	GY3526

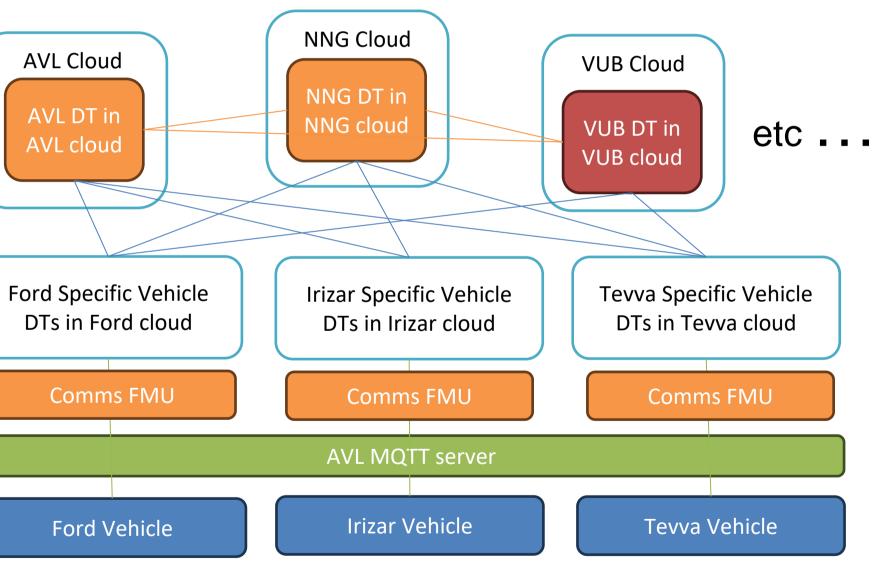


Innovation Areas 2

Flexible, fast bi-directional communications framework

- <1s round trip time secure comms (semi-realtime)
- Full Software and Hardware implementation
 - AVL or Local Cloud deployment
- Multi-cloud endpoint
 - Security and protocol support
 - Latency investigation

work ne)



Possible final solution with multiple cloud environments









